AcraDyne®
A Division of AIMCO

Gen IV iPC Controller Operation Manual

AIMCO

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1. Safety Information

General Power Tool Safety Warnings

WARNING

Read all safety warnings, instructions, illustrations, and specifications provided with this power tool. Failure to follow all instructions listed below may result in electric shock, fire, and/or serious injury.
Save all warnings and instructions for future reference.

1. Work area safety

a. Keep work area clean and well lit.
b. Do not operate power tools in explosive atmospheres, such as in the presence of flammable liquids, gases, or dust.
c. Keep children and bystanders away while operating a power tool.

2. Electrical safety

a. Power tool plugs must match the outlet. Never modify the plug in any way. Do not use any adapter plugs with earthed (grounded) power tools.
b. Avoid body contact with earthed or grounded surfaces, such as pipes, radiators, ranges, and refrigerators.
c. Do not expose power tools to rain or wet conditions.
d. Do not abuse the cord. Never use the cord for carrying, pulling, or unplugging the power tool. Keep cord away from heat, oil, sharp edges, or moving parts.
e. When operating a power tool outdoors, use an extension cord suitable for outdoor use.
f. If operating a power tool in a damp location is unavoidable, use a residual current device (RCD) protected supply.

3. Personal safety

a. Stay alert, watch what you are doing, and use common sense when operating a power tool. Do not use a power tool while you are tired or under the influence of drugs, alcohol, or medication.
b. Use personal protective equipment. Always wear eye protection.
c. Prevent unintentional starting. Ensure the switch is in the off-position before connecting to power source and/or battery pack, picking up or carrying the tool.
d. Remove any adjusting key or wrench before turning the power tool on.
e. Do not overreach. Keep proper footing and balance at all times.
f. Dress properly. Do not wear loose clothing or jewelry. Keep your hair, clothing, and gloves away from moving parts.
g. Do not let familiarity gained from frequent use of tools allow you to become complacent and ignore tool safety principles. A careless action can cause severe injury within a fraction of a second.

4. Power tool use and care

a. Do not force the power tool. Use the correct power tool for your application.
b. Do not use the power tool if the switch does not turn it on and off.
c. Disconnect the plug from the power source and/or remove the battery pack, if detachable, from the power tool before making any adjustments, changing accessories, or storing power tools. Such preventive safety measures reduce the risk of starting the power tool accidentally.
d. Store idle power tools out of the reach of children and do not allow persons unfamiliar with the power tool or these instructions to operate the power tool. Power tools are dangerous in the hands of untrained users.
e. Maintain power tools and accessories. Check for misalignment or binding of moving parts, breakage of parts, and any other condition that may affect the power tool's operation. If damaged, have the power tool repaired before use. Many accidents are caused by poorly maintained power tools.
f. Use the power tool, accessories, and tool bits, etc., in accordance with these instructions, taking into account the working conditions and the work to be performed. Use of the power tool for operations different from those intended could result in a hazardous situation.
g. Keep handles and grasping surfaces dry, clean, and free from oil and grease. Slippery handles and grasping surfaces do not allow for safe handling and control of the tool in unexpected situations.

5. Service

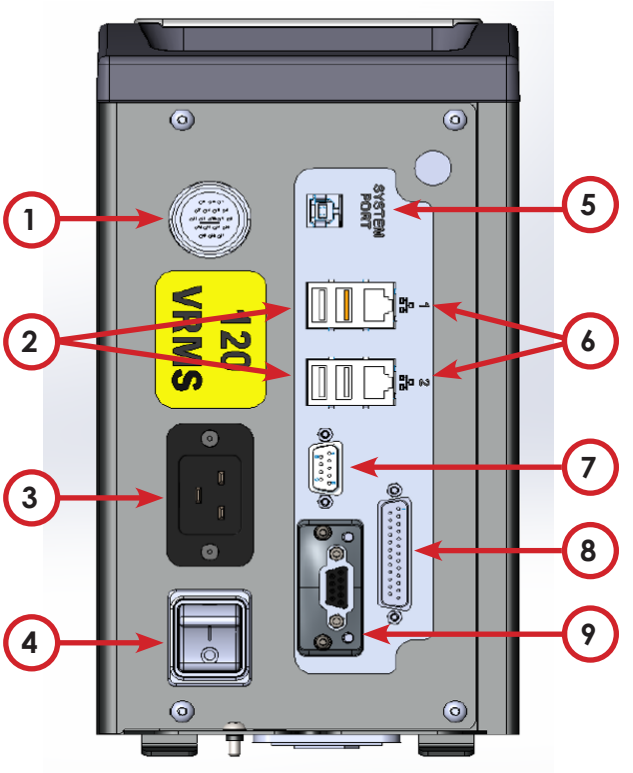
a. Have your power tool serviced by a qualified repair person using only identical replacement parts. This will ensure that the safety of the power tool is maintained.

6. Equipment Installation, Operation, and Maintenance

a. Safety of any system incorporating the equipment is the resposibility of the system assembler
b. Position the equipment so that it is easy to access the disconnecting device
c. Do not replace main power cord with an inadequately rated cord
d. Only allow your power tool to be repaired by a qualified technician using only original spare parts, available from AIMCO. This ensures that the safety of your device is maintained.

2. Controller Diagram

2.1 Bottom Panel



1	Tool Connection
2	USB port-for import/export of data including firmware updates
3	Power Cord Connection
4	Power Disconnect Switch-Turns controller on and off.
5	System Port- USB connection used to connect external computer to configure/monitor the controller.
6	Ethernet Port RJ45: Connection used to connect external computer to configure/ monitor the controller.
7	Serial Port (DB-9 Pin M) Serial data Output for communication with peripherals such as barcode readers and printers
8	24 Volt I/O Connector (DB-25 Pin M): Input and output of signals for process control.
9	Anybus-To connect to customer's fieldbus network (Ex: Profibus)

2.2 Front Console LED Display

Indicator Lights

Green	Indicates fastening cycle meets specified parameters.
Red	Indicates fastening cycle rejected for exceeding high torque.
Red Flashing	Indicates low torque. Fastening cycle was rejected for not achieving low torque.
Yellow	Indicates High Pulse. Fastening cycle was rejected for exceeding high pulse.
Yellow Flashing	Indicates Low Pulse. Fastening cycle was rejected for not achieving low pulse.
Blue	Tool is In-cycle, above threshold.

Torque Display
Always displays torque value

Secondary Display
Toggle button switches secondary display between
- Units of measure
- Ethernet 1 IP address
- Ethernet 2 IP address
- USB (System Port) IP address
- Angle report

NOTE: If Jobs are enabled refer to "4.3 Job" on page 14 for Toggle Button function.

Toggle Button
Toggles what is shown in the secondary display

Parameter Settings (PSet)/Job Display

Increment/Decrement Buttons
Change PSet

3. Initial Setup

Step 1: Connect Sensor Cable to CN-1 Connector of IPC Controller (Figure 1, pg.) and connect Amphenol Connector to the tool.

Step 2: Plug female end of power cable into Power Cable Connector.

Step 3: Plug male end of power cable into appropriate power source. Connection to local power should be made in consultation with a qualified electrician.

Step 4: The Secondary Protective Earth Attachment (it is required) must be connected to ground using the #14 AWG conductor, a green wire with a yellow stripe. Attach using a #10-14AWG ring terminal and #10 star washer (see Figure 1).

Figure 1 — Secondary Protective Earth Attachment

Step 5: Turn controller on by pushing the Power Disconnect Switch to the POWER ON position, a light indicates power on.

3.1 Connecting to the Controller

There are three ways to program/communicate with the controller:

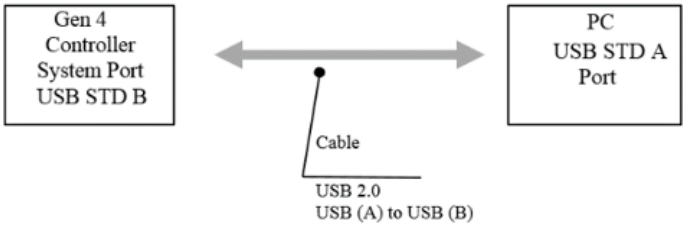
- Controller touch-screen console
- System Port: (USB A to B connection) Direct connection to controller.
- Ethernet Port: Via direct connection or LAN.

Touchscreen Console

Controller functions and programming can be accessed directly through the touch-screen.

1. Power on controller.
2. Run screen will appear
3. Controller is ready for use.

Connecting via the System Port Directly to PC



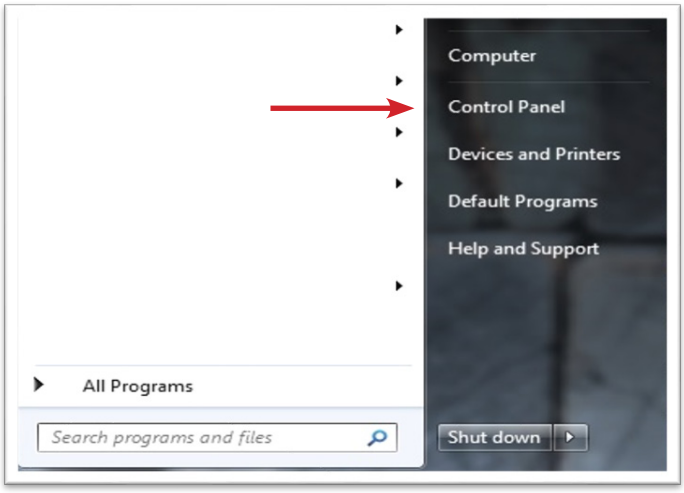
The following is an example using Window 7. Your screen may look different depending on the operating system.

Windows USB Setup

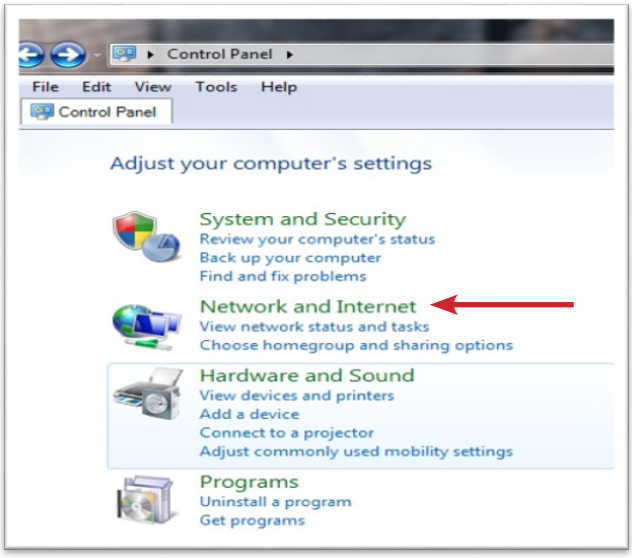
Step 1: Power on PC and controller, allow enough time for them to become fully operational.

Step 2: Attach controller to PC using a USB 2.0 A-B cable. If this is the first time connecting the devices, wait for Windows to install the RNDIS driver. This should happen automatically.

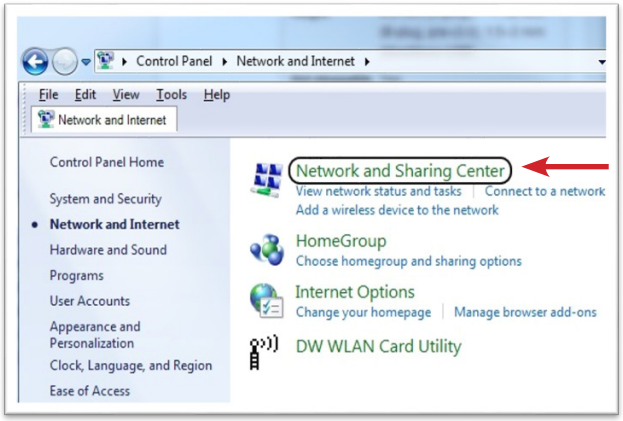
Step 3: After the driver is installed, go to 'Control Panel'.



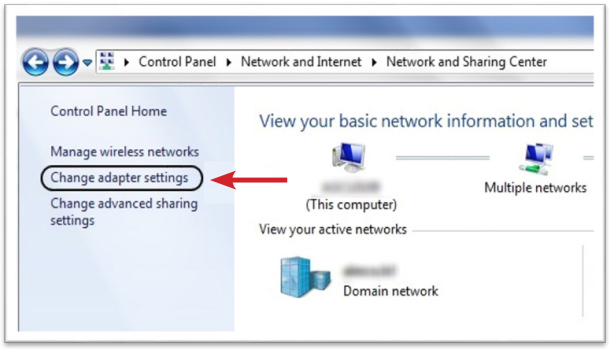
Step 4: Go to 'Network and Internet'.



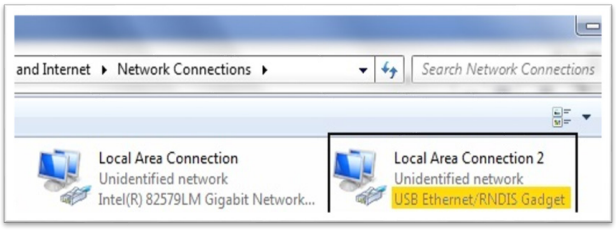
Step 5: Go to 'Network and Sharing Center'.



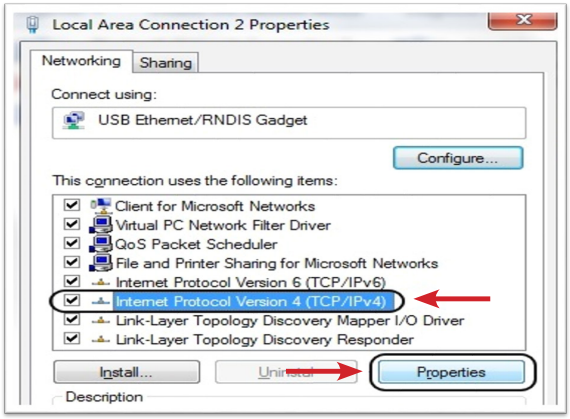
Step 6: Go to 'Change adapter settings'.



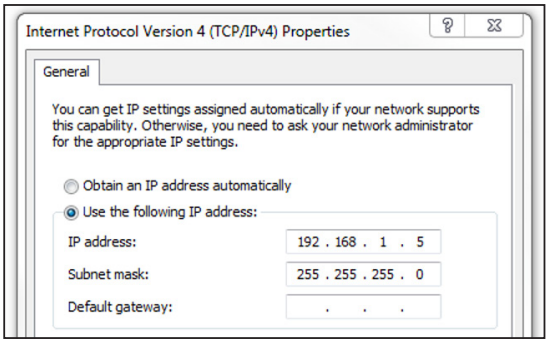
Step 7: Find the Local Area Connection that is using the 'USB Ethernet/RNDIS Gadget' network. Right click this network and go to 'Properties'.



Step 8: In Properties window select 'Internet Protocol Version 4' and click 'Properties'.

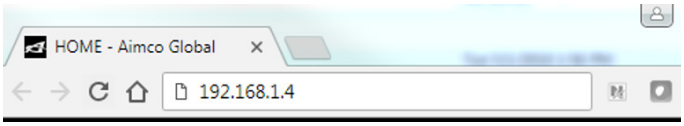


Step 9: In 'Properties', set the IP address to a static address.



Type an IP address of 192.168.1.5 (Any address on the same subnet as the controller will work). Set subnet mask to 255.255.255.0

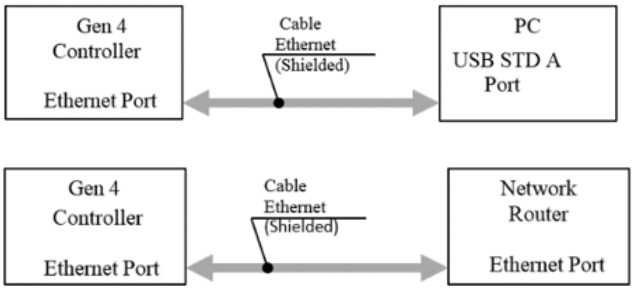
Step 10: To connect to the controller, open a browser such as Chrome or Firefox. Enter 192.168.1.4, the default system port IP address.



You will see the controller software on your computer screen.

NOTE: Controller does not have a DHCP client, it will not automatically configure itself with a usable IP address. Consult your Network Administrator for configuring a correct IP address for your network. The PC, Laptop or Tablet IP address will need to be configured to communicate with the controller.

Connecting using the Ethernet Port Directly or via LAN to PC

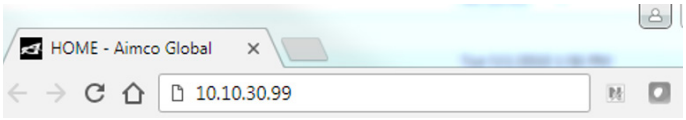


Turn on the computer and make a physical connection by using a straight through Ethernet cable.

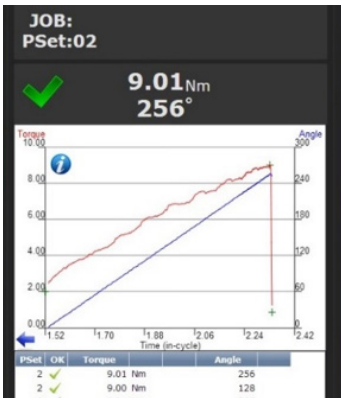
Turn on controller. Verify the controller IP address in 'Communication Interfaces' or press toggle button to verify the IP address. If defaulted 0.0.0.0 set desired IP address.

Set a static IP address of the Computer/Laptop to 10.10.30.98 (example) and subnet mask to 255.255.255.0. (For instructions, see the example in "Step 9" earlier in this section.)

To connect to the controller. In the Computer/Laptop open a browser such as Chrome or Firefox. Enter 10.10.30.99, the default Ethernet port IP address.



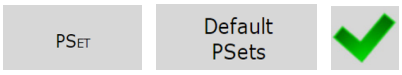
You will see on your computer screen the controller software



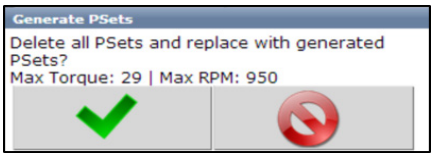
NOTE: Controller does not have a DHCP client, it will not automatically configure itself with a usable IP address. Consult your Network Administrator for configuring a correct IP address for your network. The PC, Laptop or Tablet IP address will need to be configured to communicate with the controller.

3.2 Quick Setup (Default PSets from Tool)

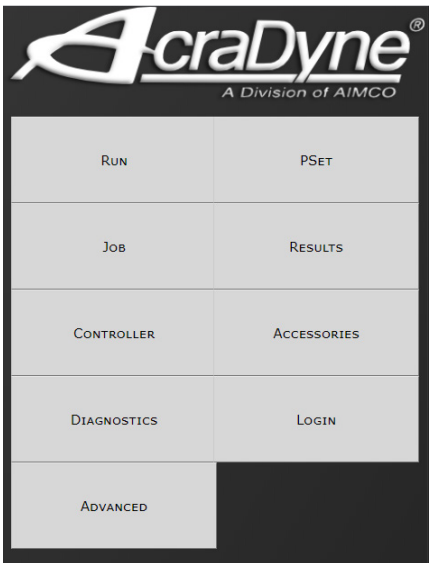
On the Home Page press the following to accept default PSet Parameters:



This will generate three generic PSets for the tool connected to the controller. It will automatically use the 40%, 60%, and 80% of the rated maximum torque of the tool in a two-stage Torque Control Pulse Monitor Strategy (TC_PM). A prompt will display rated Max Torque and Max RPM of the connected tool for reference. These Psets can be modified to meet application requirements.

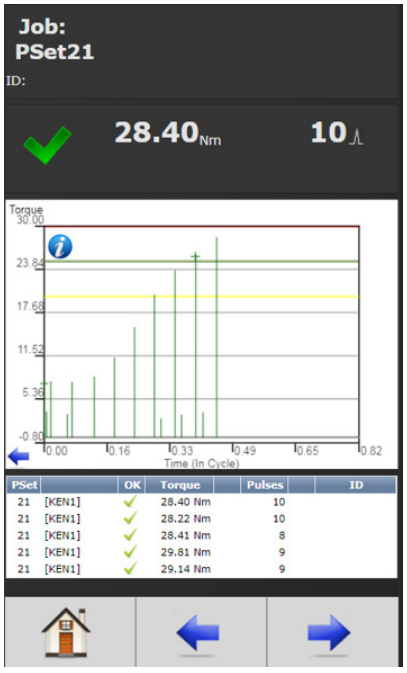


4. Home Page (Main Menu)



4.1 Run

The Run Screen is essentially the dashboard of the Gen IV controller and provides a look at real-time information regarding rundowns.



Time (In-Cycle) Screen

JOB:	Indicates the current JOB.
PSet:01	Indicates the current PSet in which you are operating.
✓	Indicates accepted rundown.
✗	Indicates failed rundown.
28.40Nm	Displays Torque and Angle for current rundown.
10	Number of Pulses

Graph displays curves representing Torque (green trace).

The blue left arrow at the origin of the graph will change the X-axis of the rundown curve from Time (In – Cycle) to Time (Overall) and Angle.

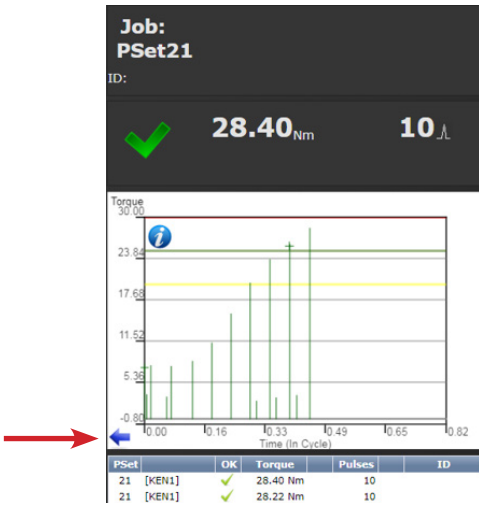
Below the graph is a historical table that will give information and status of the most recent rundowns, including current PSet, accepted/failed rundown status,torque and angle.

Arrows allow user to scroll left or right for viewing real time Job information such as Run Screen or rundown indicators.

Home tab will return user to the Home Page

Click  for curve detail.

Click on blue arrow to change curve X axis.



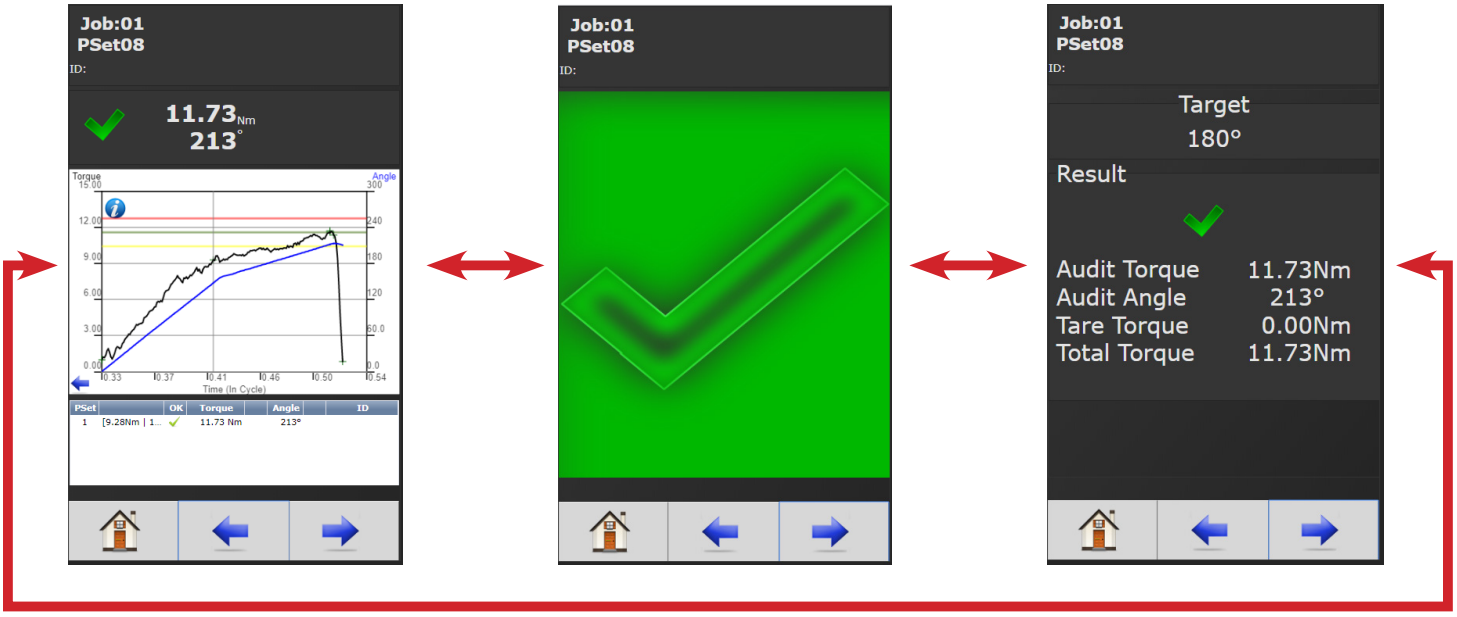
Choose Time In-cycle or Time Overall screen.

Run Screen displays real time Job information.

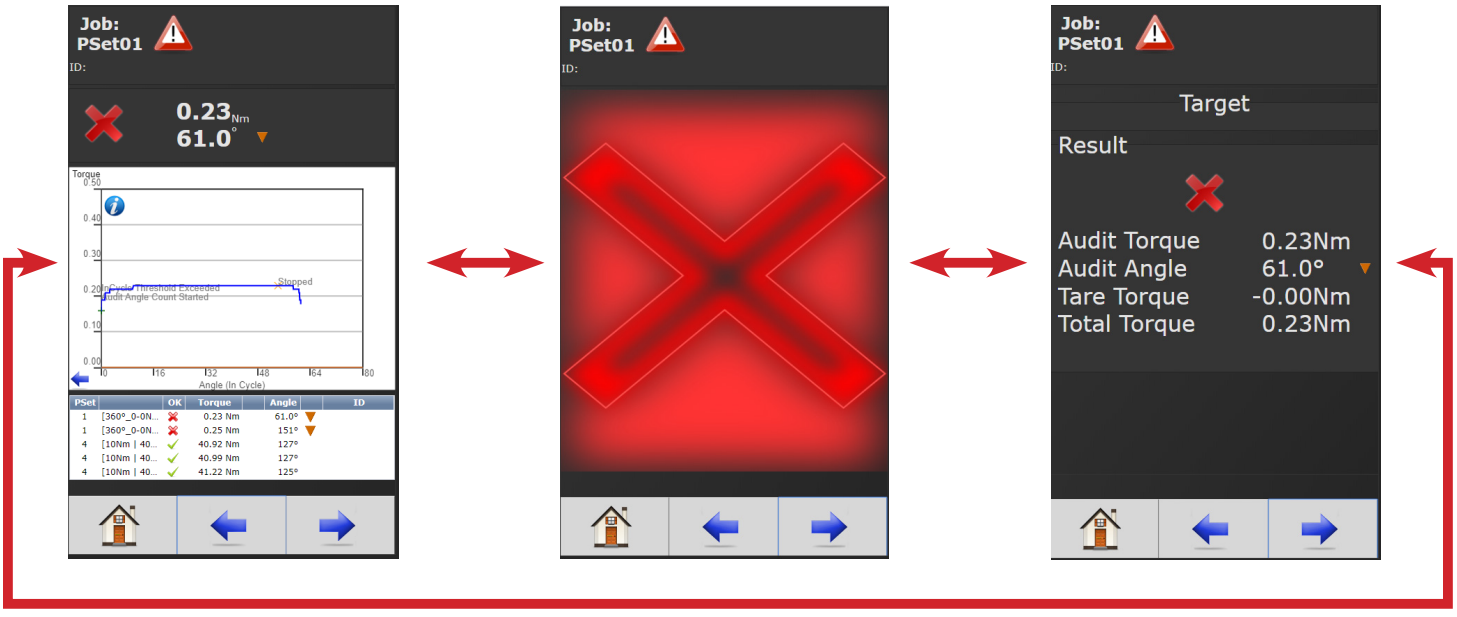
Large Screen Indicators and Audit information

The large screen indicators are helpful in viewing real time results of the rundown from a distance.

Example of Accepted Job



Example of Failed Job



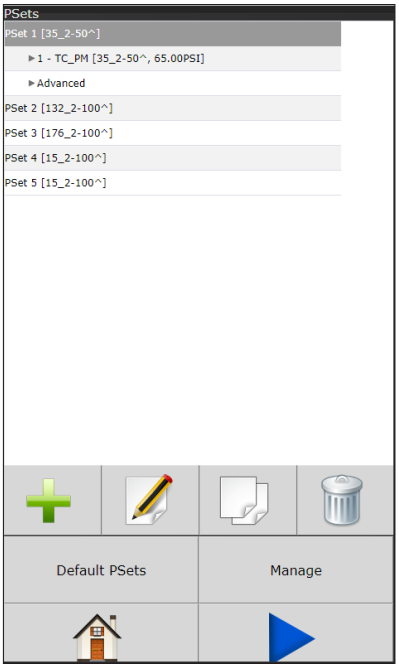
4.2 PSet

Parameter Settings (PSets) control the fastening process. The following describes the different fastening strategies and how to setup the basic PSet parameters necessary to perform a fastening. Up to 256 PSets are available.

4.2.1 Add New PSet

On Home Page press the PSET tab.

On PSets screen press to add a new Pset.



Add a PSet

Edit a PSet

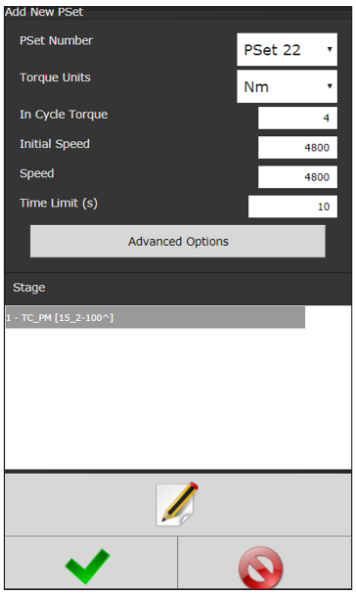
Coy a PSet

Delete a PSet

Default PSets (See "3.2 Quick Setup" on page 7)

Manage (see "4.2.5 Manage PSets" on page 13)

On Add New PSet screen (below) enter appropriate values.



PSet Number: Current PSet to be added.

Torque Units: Unit of measure.

In Cycle Torque: Threshold value at which tool is "In Cycle" and results from the Rundown will be reported.

Speed: This is the tool output speed in RPM after in-cycle torque

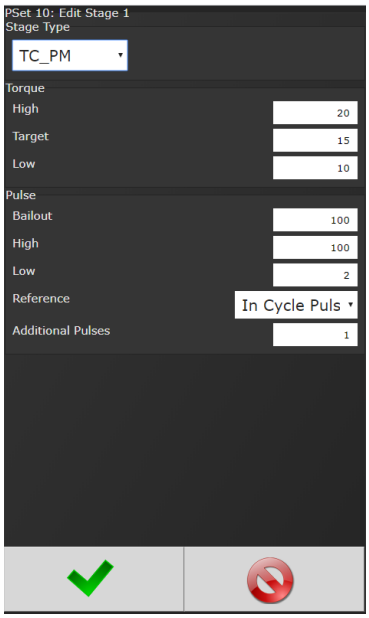
Time Limit(s): Maximum allowable time (in seconds) tool is allowed to run.

Advanced Options: (see "4.2.4 Advanced Options" on page 12)

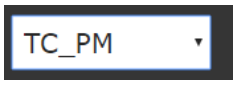
Once PSet values are entered press to enter Edit Stage screen (shown in the following section).

4.2.1.1 Add New Stage

A single stage or multiple stages build a PSet. Up to 20 stages can be assigned per PSet.



The following stage option is available:

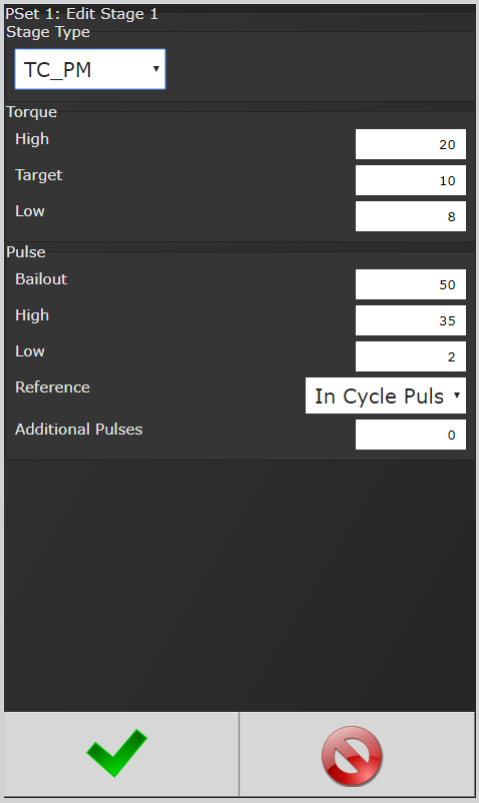


Once the desired stage(s) are selected and configured, press to save stage and again to save the PSet and return to initial PSet menu.

Next Press to go to the RUN screen or to return to the Home page. The tool should now be operational and you are ready to run a configured PSet.

4.2.2 PSet Stages

4.2.2.1 TC_PM Torque Control Pulse Monitor



Torque High: Upper control limit of the rundown.

Torque Target: Final desired torque (CUT Level).

Torque Low: The lower control limit of the rundown.

Pulse Bailout: Total number of pulses never to be exceeded. Helps to illustrate how far past Pulse High the rundown experienced without damaging the part or excessively wearing the tool's pulse fluid.

Pulse High: Maximum acceptable pulses

Pulse Low: Minimum acceptable pulses

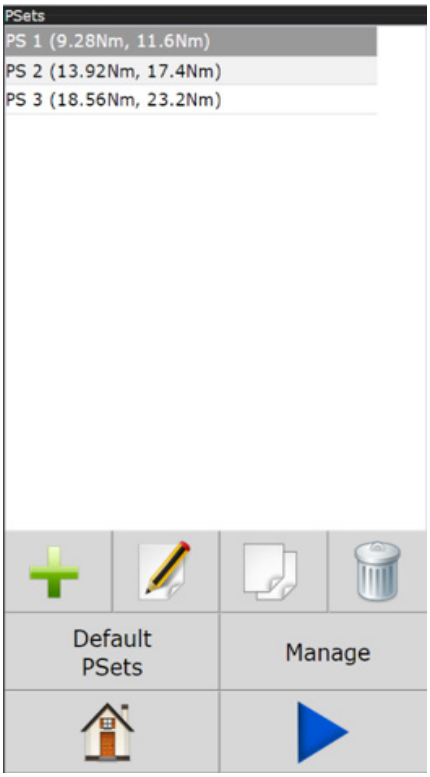
Pulse Reference: (drop down menu)

- **In-cycle Pulse:** Monitoring number of tool Pulse begins after the tool overcomes pre-set in-cycle Torque
- **Stage Pulse:** Monitoring all Pulses specifically in the Stage

Additional Pulses: After reaching target torque, additional pulses to be applied before shutting of the air to the tool.

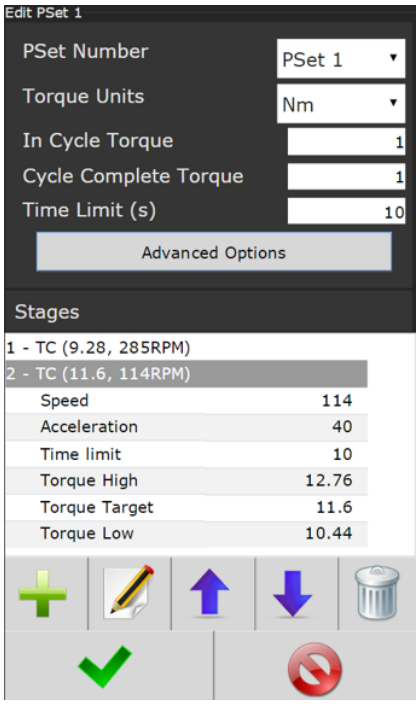
4.2.3 Edit PSet

On Home page press PSET

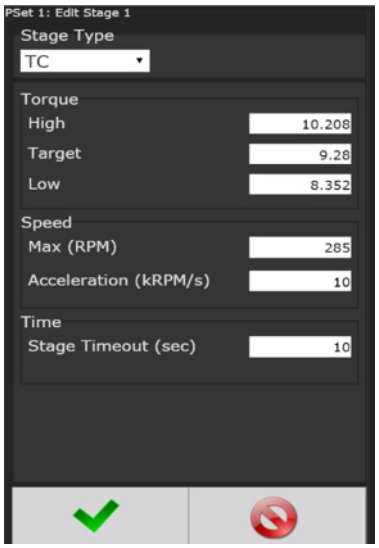


On the PSet screen click on the desired PSet you would like to edit.

Click on the Edit button to make changes in the Edit screen (below).

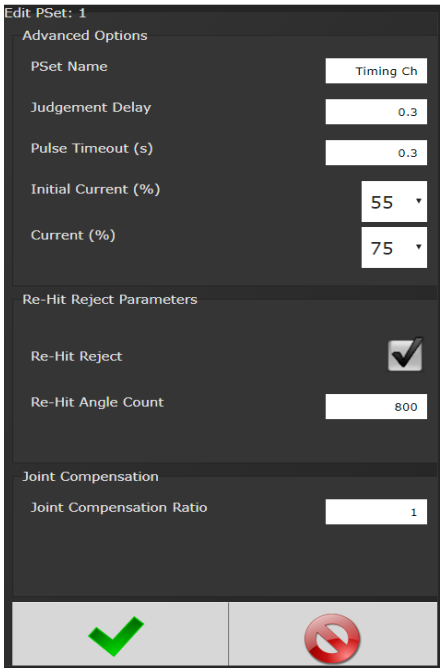


If further Stage changes are needed click the Edit button again to enter Edit Stage screen (below).



Once desired changes are made click twice to save changes.

4.2.4 Advanced Options



PSet Name: Add PSet name if desired (up to 10 characters).

Judgement Delay: Tool provides judgment after tool stops producing pulses and this delay expires.

Pulse Timeout: After in-cycle is reached the tool will stop running and end the fastening if the time between pulses exceeds this value

Initial Current (%): Percentage of maximum current delivered to the motor before in-cycle torque threshold. Reduce this value to reduce the amplitude of torque pulses.

Current (%): Percentage of maximum current delivered to the motor after in-cycle torque threshold.

Re-hit/Reject Parameters: Prevents the fastening of an already tightened fastener. If enabled, tool will stop and the rundown will be aborted, if the angle of rotation between the Re-Hit Reference Torque and the In-Cycle Torque is less than the Re-Hit Angle Count.

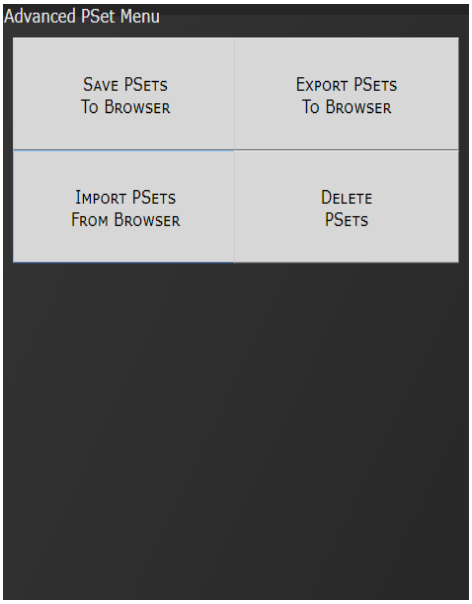
NOTE: If the attempted rundown is a Re-Hit, it will not be reported or recorded.

Re-Hit Reject: Prevents the fastening of an already tight fastener. If enabled,the tool will stop and the rundown will be aborted,if the angle of rotation between the - - - - and In Cycle Torque is less than the Re-Hit Angle Count.

Re-Hit Angle Count: The default Re-Hit Angle Count is 100 degrees. If the angle changes less than 100 degrees in .04 seconds before the in-cycle pulse it is determined to be a Re-Hit.

Joint Compensation Ratio: Adjusts the target torque of the tool to compensate for joint characteristics. This value has an inverse relationship with the target torque (Output torque = Target Torque / Ratio). Ratio values above 1.0 result in a lower output torque where values below 1.0 result in higher output torques.

4.2.5 Manage PSets



Save PSets to Browser
Allows the PSet information to be saved to the local PC connected to controller. PSet information is saved as a .txt file and can be opened using any text editor such as WordPad. It can also be opened with Excel. The format of the .txt file is tab separated values.

Export PSets to Browser
Save the PSets as a database file to the PC connected to controller. These PSets can later be imported to another controller.

Import PSets from Browser
Import previously exported PSets to controller.

Delete PSets
Enables deletion of selected PSets.

4.2.6 Multistage Rundown Evaluation and Reporting

- If a rundown cycle completes, or is terminated early while in or after the final stage of the PSet:
  - The overall evaluation of the rundown will be determined using the limits set in the final stage.
  - The peak torque, pulse count, and angle, achieved during the rundown are used for the evaluation and reported.
  - Note: The fastening torque must reach the In-Cycle torque value set in the PSet in order for the rundown to be evaluated and reported.

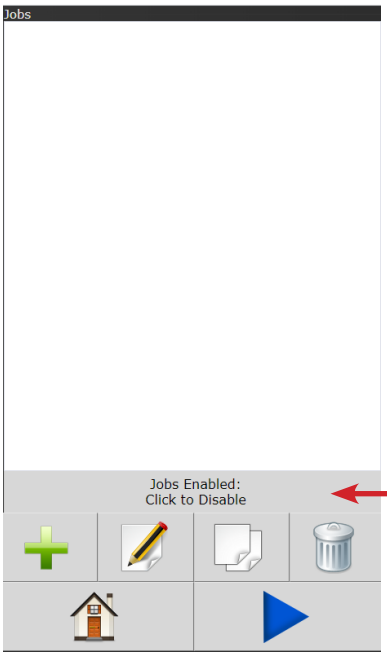
- If a rundown is terminated early before reaching the final audit stage:
  - The overall result of the rundown will be reported as a reject.
  - The torque, pulse, and angle evaluation will be determined using the limits set in the stage that was running when the rundown was terminated.
  - The peak torque, pulse count, and angle at the point in time when the rundown was terminated, is used for the stage evaluation.
  - The torque, pulse count, and angle status reported will reflect this stage evaluation with the following exception:
    - If torque, pulse count, and angle are all within limits of the stage that was running, the torque, pulse, and angle status will all be reported as low. This is done to further indicate that the rundown terminated before reaching the final audit stage.
  - The peak torque, pulse count, and angle achieved, during the rundown, will be reported.

- Angle measurement details:
  - Peak Angle used for overall evaluation and reported is the peak angle achieved during the rundown, measured from the angle reference set in the final stage. Note: If an angle reference is not defined in the final audit stage, the angle is measured from when the torque first crosses the In-Cycle torque set in the PSet.
  - Angle used for stage evaluation is the angle at the point in time when stage was terminated or completed, measured from the angle reference set in the stage.

- Note: If the evaluation of any stage during the rundown fails, or a bail out limit is exceeded, the fastening cycle will be terminated early and any subsequent stages will not run.

4.3 Job

A Job is a collection of PSets which can be run when performing multiple fastening operations on a single application.



Jobs provide:
- Error proofing
- Logical grouping of PSets
- Fastening order
- Job status

Click to Enable/Disable Job function.

4.3.1 Add New Job

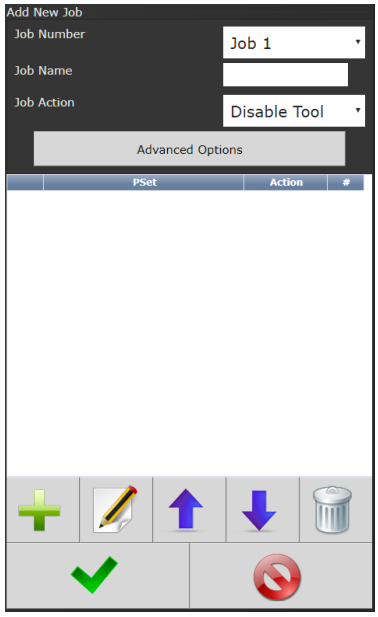
To add a new Job press 

on the Home Page.
Press  on Jobs screen (above) to enter Add New Job screen (below)

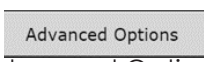
Job Number: Up to 99 Jobs can be configured.

Job Name: Enter Job Name

Job Action:
- **Disable Tool:** Disable tool after job is finished. Job complete Icon will appear.  Tool will not operate until job is reset.

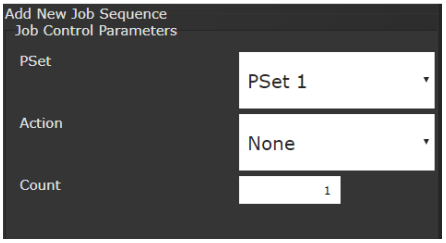


- **Reset Job:** Will reset after Job is finished.

Enter Advanced Options 

if needed (see next section "4.3.2 Advanced Options")

After appropriate values are entered, press + to go to Add New Job Sequence screen.



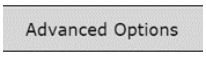
PSet Number: Choose any current PSet already configured in controller.

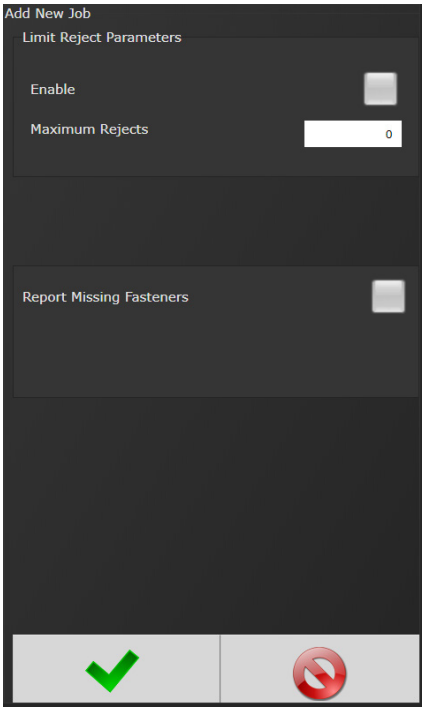
Action:
- **None:** Will stay in current sequence.
- **Next:** will advance to next sequence set up after count is reached.

Count: Fastener number required to complete sequence.

Once values are entered press ✓ two times to return to Job screen

4.3.2 Advanced Options





Limit Reject Parameters:
- **Enable:** Enable or Disable
- **Maximum Rejects:** Number of rejected fasteners allowed

Report Missing Fasteners: Add an option to each JOB to allow the reporting of any missing fasteners. When it is set the controller will report an NOK rundown for each fastener that is defined in the JOB but has not been ran. These NOK results will be reported whenever a new job is started AND the prior JOB is incomplete.

These generated NOK results are treated like any other fastening. They are displayed on the run screen, stored in the results and transmitted on all protocols.

4.3.3 Jobs "Enabled" Display and Button Function

- Increment and Decrement buttons change the job sequence. The pset number will change and job sequence number on secondary display will change if jobs are enabled.
- Holding the toggle button will display will display the Job number, while pressing increment or decrement buttons will change it. The two numbers on the PSet/Job display will be separated by decimals.
- Pressing the toggle button will change secondary display between:
  - Units of measure
  - Ethernet IP address
  - System port IP address
  - Angle report
  - Bolt count
  - Job sequence
  - Pulse count

NOTE: Job sequence shows which PSet you are currently on in the job (this is not the pset number). The first pset in the job is always job sequence 1, and the next is 2, etc.

Bolt count is shown as current bolt count out of total number of bolts. Example: If you have 3 total bolts. When you start the job you will see 0.3. After one rundown you will see 1.3 and then 2.3 on the next run and so on until the job is completed.

4.4 Results

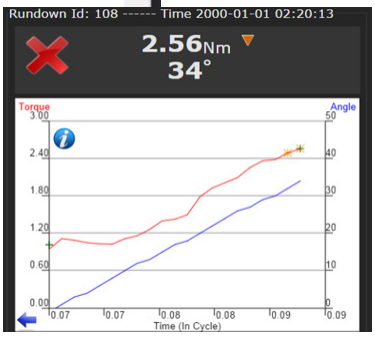
ID	Time Stamp	PS...	OK	Torque	Angle
585	01-07 19:13:02	2	✓	17.46 Nm	341
584	01-07 19:12:59	2	✓	17.77 Nm	351
583	01-07 19:12:57	2	✓	17.93 Nm	372
582	01-07 19:12:52	2	✓	18.09 Nm	350
581	01-07 19:12:50	2	✓	17.61 Nm	338
580	01-07 19:12:48	2	✓	18.03 Nm	359
579	01-07 19:12:46	2	✓	17.46 Nm	354
578	01-07 19:12:43	2	✓	18.13 Nm	377
577	01-07 19:12:41	2	✓	17.59 Nm	359
576	01-07 19:12:36	2	✓	17.76 Nm	377
575	01-07 19:12:33	2	✓	17.76 Nm	359
574	01-07 19:12:29	2	✓	17.70 Nm	377
573	01-07 19:12:27	2	✓	17.58 Nm	358
572	01-07 19:12:22	2	✓	17.97 Nm	384

This screen provides a history of rundowns performed. Information such as ID Number, Time Stamp, Parameter Set#, Accept /Reject status, and Torque and Angle are recorded for each rundown.

	Deletes individual rundowns by clicking on them separately and deleting them in the next screen or deleting all rundowns by clicking on the icon at the bottom of Results page. A Confirmation screen will appear. 
	Save Button saves rundowns as .Txt File.
	Filter Button gives filter options in Rundown screen.
	Home Button returns to main display menu.
	Play Button sends you directly to Run Screen.
	Refresh Button refreshes screen to include latest rundowns.

ID	Time Stamp	PS...	OK	Torque	Angle
112	01-01 02:29:00	1	✓	12.03 Nm	124
111	01-01 02:28:56	1	✓	11.98 Nm	124
110	01-01 02:28:50	1	✓	12.02 Nm	112
109	01-01 02:28:46	1	✓	11.63 Nm	113
108	01-01 02:20:13	1	✗	2.56 Nm	34

Click on Individual Runs for Rundown information.



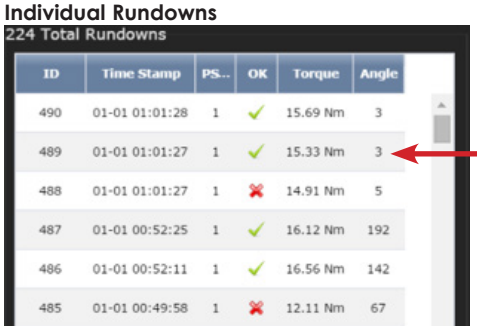
Example: Rejected Rundown Information.

4.4.1 Saving Rundown(s)

Click on  in main rundown screen to view/save total rundowns.

Then click on  on the PC to save or open the file using a text editor such as Notepad. The format of the Rundown file is tab separated variables and can be viewed using Excel. The raw data can now be imported to Excel to build graphs, charts etc. Contact AIMCO Technical Service for pre-made Torque and Angle Templates.

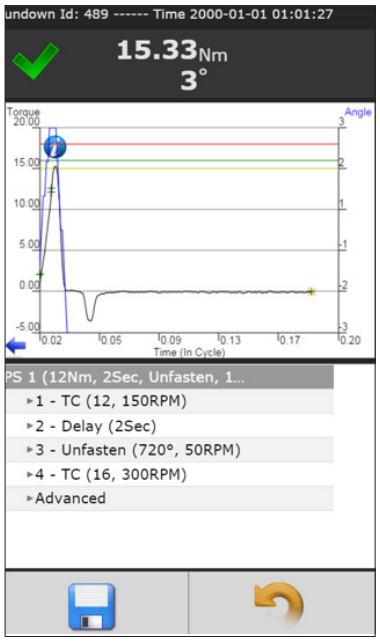
Individual Rundowns



ID	Time Stamp	PS...	OK	Torque	Angle
490	01-01 01:01:28	1	✓	15.69 Nm	3
489	01-01 01:01:27	1	✓	15.33 Nm	3
488	01-01 01:01:27	1	✗	14.91 Nm	5
487	01-01 00:52:25	1	✓	16.12 Nm	192
486	01-01 00:52:11	1	✓	16.56 Nm	142
485	01-01 00:49:58	1	✗	12.11 Nm	67

Click on an individual run to view/save rundown information

Rundown Information View

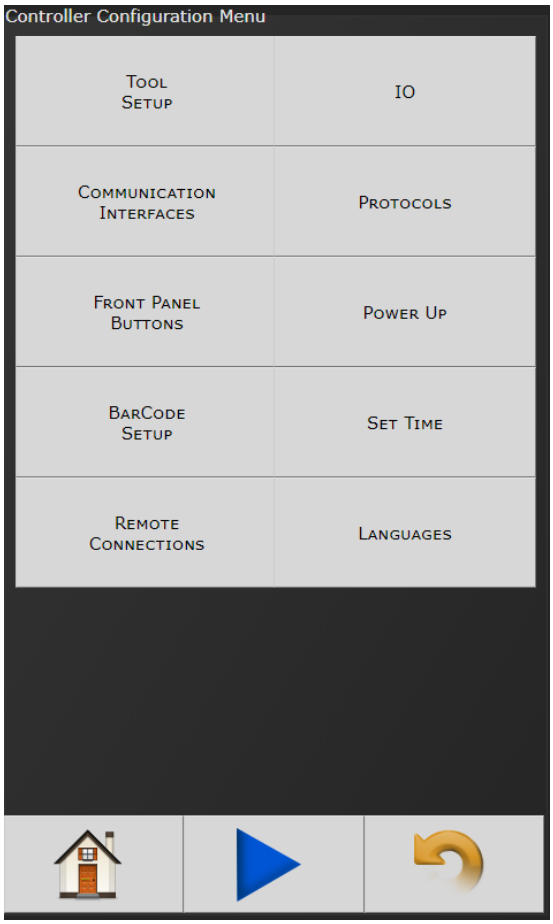


Sample of Individual Rundown Information

1	Result	65	
2	Job Numb	1	
3	Job Name	Paramont	
4	Job Seque	1	
5	Bolt Coun	3	
6	Date	########	4:18:00
7	Master Ru	0	
8	PSet ID	59	
9	PSet Num	1	
10	PSet Name		
11	Tool Mod	AEN32030A	
12	Tool Seria	191111	
13	Torque	11.69	
14	Angle	57	
15	Pulses	0	
16	Torque St	P	
17	Angle Stat	--	
18	Pulse Stat	--	
19	Rundown	P	
20	Tool Cycle	1111	
21	ID1 ("ID #1	2.2E+10	
22	ID2 ("ID #2	4.86E+10	
23	ID3 ("ID #3")		
24	ID4 ("ID #4")		
25			
26			
27			
28	Curves		
29	Tick	Torque	Angle
30	0	0.02	0
31	1	0.02	0
32	2	0.05	0
33	3	0.04	0
34	4	0.09	0

4.5 Controller

The controller menu is where all of the settings for the Gen IV controller are configured. All of the different configuration capabilities are explained below.



4.5.1 Tool Setup

In this screen user can enable/disable various tool functions.

4.5.1.1 Tool Parameters

For proper operation of the tool, this information must be entered each time a new tool is connected to the controller.

Tool CAL: Value stamped on tool.

CAL Ratio: Calibration factor for matching the torque reading of the tool/ controller to a torque auditor.

Maximum Torque: Rated maximum torque of the tool. This is used when determining the default PSets.

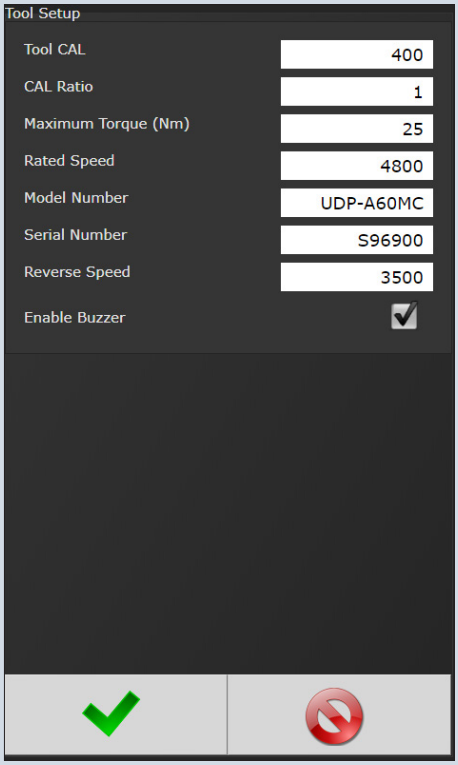
Rated Speed: Rated catalog speed of the tool. (Optional information only. Does not affect the operation of the tool)

Model Number: (Optional information only. Does not affect the operation of the tool)

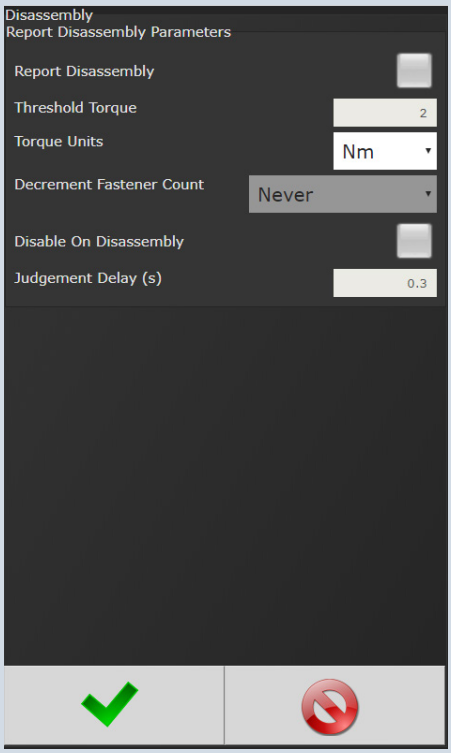
Serial Number: (Optional information only. Does not affect the operation of the tool)

Reverse Speed: The speed that the tool will run in reverse

Enable Buzzer: Enables or disables the buzzer



4.5.1.2 Disassembly



Report Disassembly: If enabled, disassembly events will be reported and logged.

Threshold Torque: Disassembly will be reported only if this torque value is reached. This is entered as a positive value.

Torque Units: Units for the Disassembly Threshold Torque

Decrement Fastener Count: If Disassembly is detected the fastener count in JOBS

- **Never:** Decrement count will be ignored
- **Always:** Decrement will always be active
- **Only after NOK:** Decrement count will only happen after a rundown judged to me NOK (Reject) has occurred

Disable on Disassembly: If disassembly is detected the tool will be disabled

Judgment Delay (s): Amount of time (in seconds) after final pulse in disassembly that determines disassembly has been completed

When a disassembly event is reported:
The disassembly will be displayed on the run screens and logged in the rundown record, containing the following:

- Overall evaluation will be marked as 'Disassembled' Peak torque during the disassembly (torque shown as negative).
- Peak overall angle during the disassembly (angle shown as negative).
- Curve data from the disassembly
- Parameters from the current PSet selected
- Fastening events from the disassembly.

All of the controller's status LEDs will be turned OFF. The LED display will show peak torque and angle as negative

I/O Considerations:
When disassembling, all assignable IO outputs that report rundown status will remain in the state from the last fastening cycle. This includes:

- Ok and Nok signals
- Torque/Angle high or low signals
- Torque and Angle Values

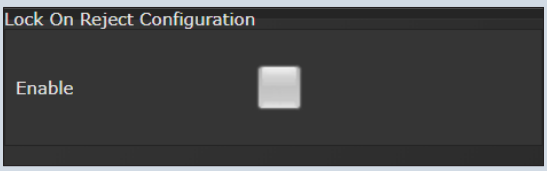
All assignable I/O outputs reporting a fasting events will not change state during the disassembly. This includes:

- Fastening Complete
- In Cycle
- Fastening Stopped
- Fastening Aborted

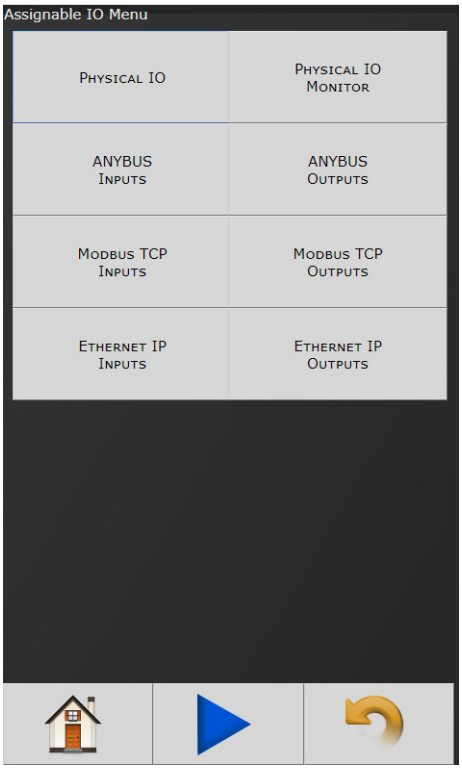
NOTE: When the tool is placed into disassembly mode, all of the tool's LEDs flash and the Horn beeps. This will continue until the tool is placed back into fastening mode.

4.5.1.3 Lock Tool On Reject

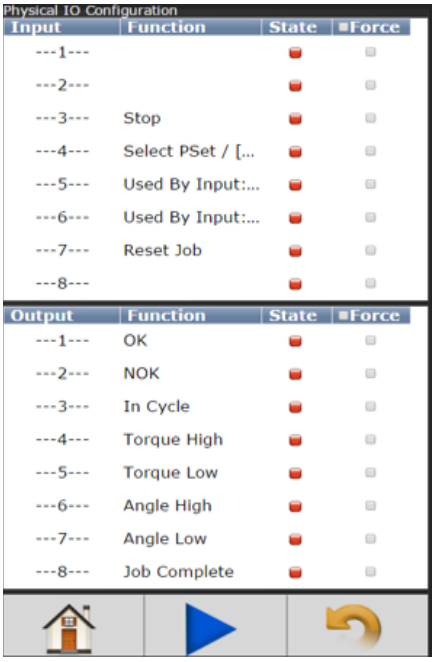
When enabled, this prevents tool from starting a new rundown if the result of the last rundown was a reject. Tool remains locked until one of the four Unlock Mode conditions above are satisfied.



4.5.2 IO



4.5.2.1 *Physical IO*



Assign functionality to 24V Input and Output pins. Shows the "live state" of each Input and Output.

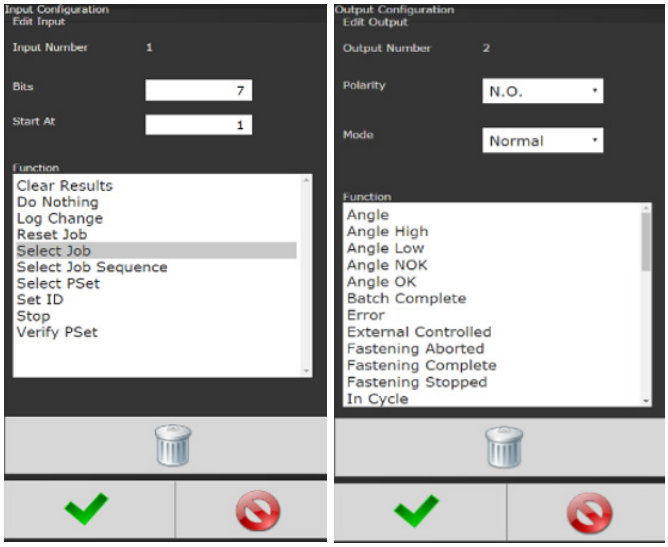
Functions shown in screen shot are default settings.

To change these assignments, click on the "Function" column of the any of the I/O pins. This will open a Output/ Input Configuration screen (following).

Click on the "Force" column of any of the I/O pins to enable or disable the forcing of the selected input or output.

If force is enabled, click on the "State" column to toggle the state of input or output selected.

Input Configuration *Output Configuration*

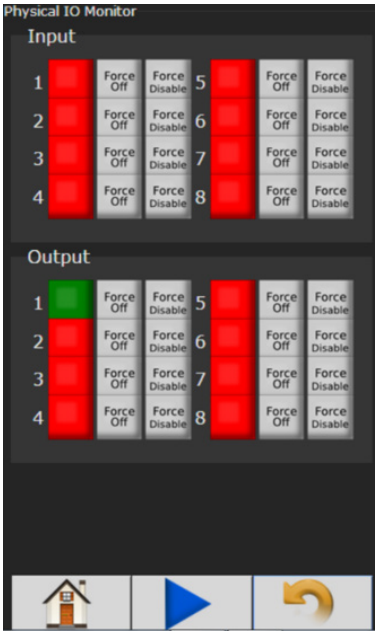


See "9. Assignable I/O" on page 42 for more details on available assignment functions and how to configure.

See "8. 24 Volt I/O" on page 40 for the pinout of the 24Volt Logic IO port, and wiring examples.

4.5.2.2 *Physical IO Monitor*

Provides monitoring of Physical 24 Volt I/O. Force on/off the individual I/O pins for testing of field wiring.

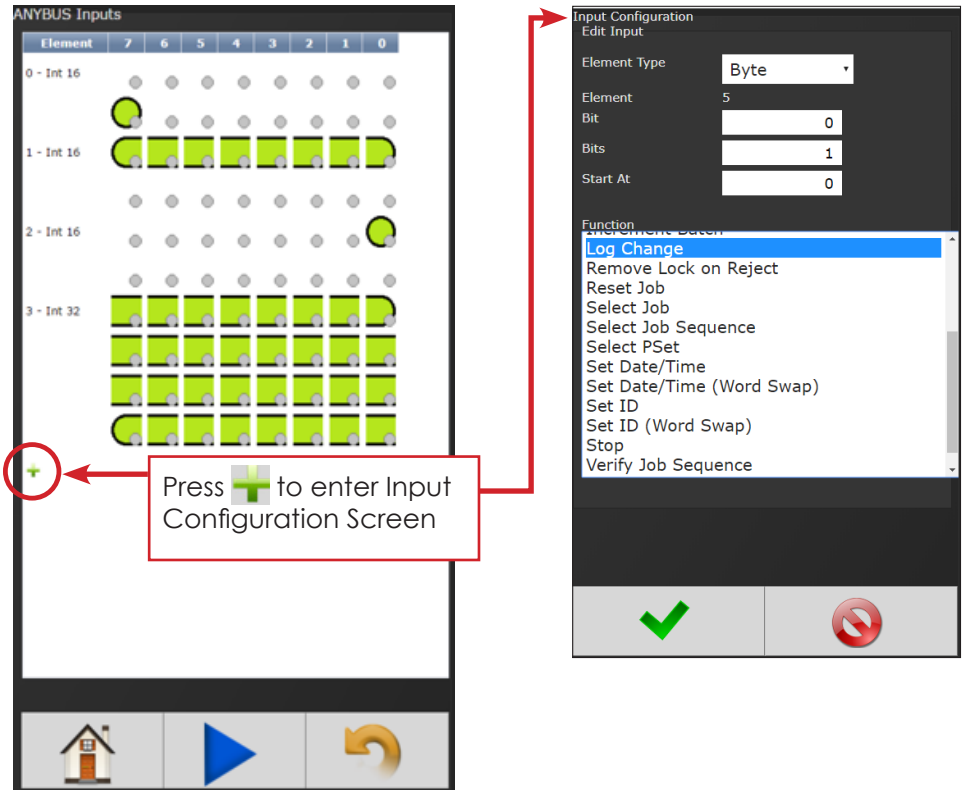


Each indicator shows the state of the associated pin.
Green = On
Red = Off

- **Force Enable/ Disable:** Enables the forcing of the selected input or output.
- **Force Off/On:** If Force is enabled this button will toggle the state of input or output selected.

4.5.2.3 Anybus/Modbus TCP/Ethernet IP Inputs

These types of communication are useful for data communication between controller and PLCs. It is an effective, quick way for the data transfer of short data packages.



Element Type: Choose from Byte, Int16, Int32, or ASCII.

Element: Shows element # being configured

Bit: Enter Bit #.

Bits: # of bits the assignment will read.

Start at: Starting bit location.

Length (not shown): Number of Characters desired to send when in ASCII ID function

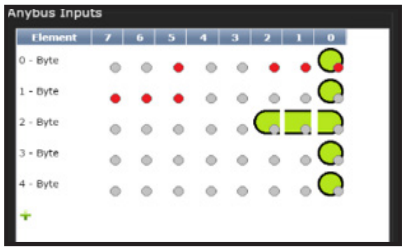
Torque (not shown): Torque value to be reported when using Click Wrench input. Value input is what will be sent from controller when Input Signal is received from a Click Wrench. ***Value is NOT calculated by the controller rather it is solely what the Click Wrench is calibrated to by outside means.***

Polarity (not shown): Select Normally Open or Normally Closed Outputs.

Function: See "9. Assignable I/O" on page 42 for more details on assignable functions.

Click on after appropriate selections are made.

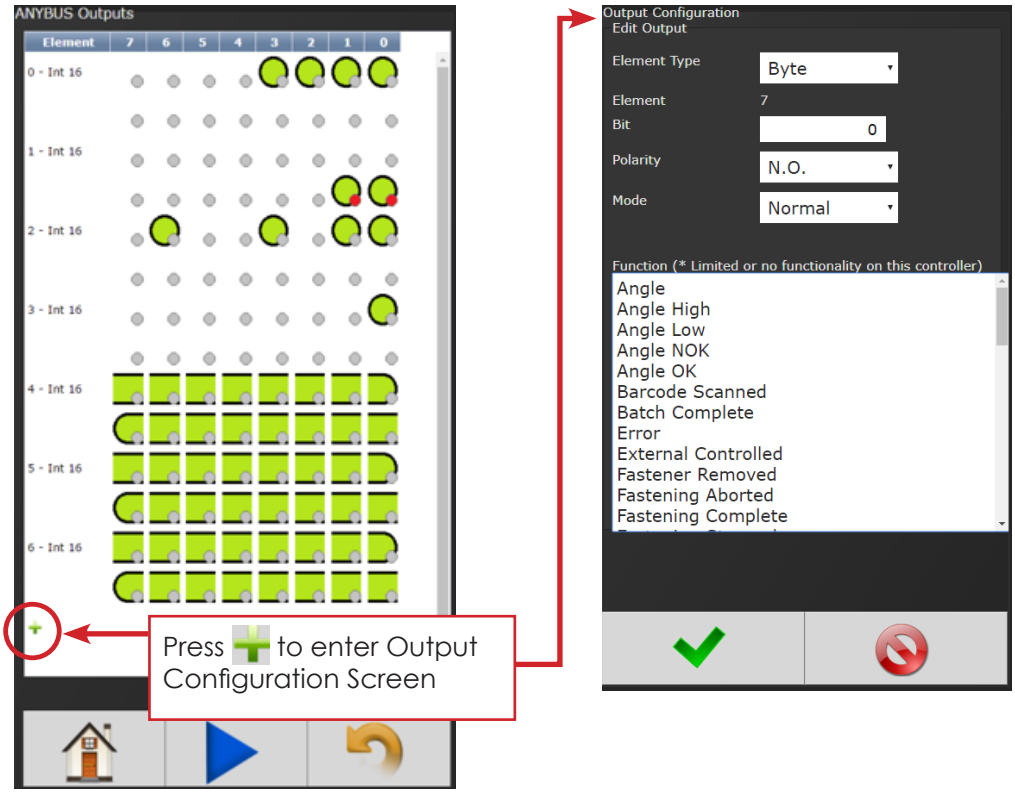
Example of the Anybus Input screen with five Inputs set up.



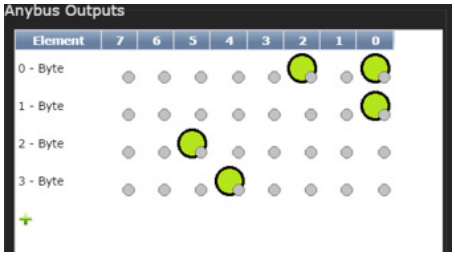
Click on to change an individual Element or return to Input Configuration screen.

Will delete individual Elements.

4.5.2.4 Anybus/Modbus TCP/Ethernet IP Outputs



Example of the Anybus Output screen with five Outputs set up.



Click on to change an individual Element or return to Input Configuration screen.

Will delete individual Elements.

Element Type: Choose from Byte, Int16, or Int32.

Element: Shows Element # being configured.

Bit: Enter Bit #

Bits (not shown): # of bits the assignment will read.

Start at (not shown): Starting bit location.

Polarity: Select Normally Open (N.O.) or Normally Closed (N.C.) Outputs.

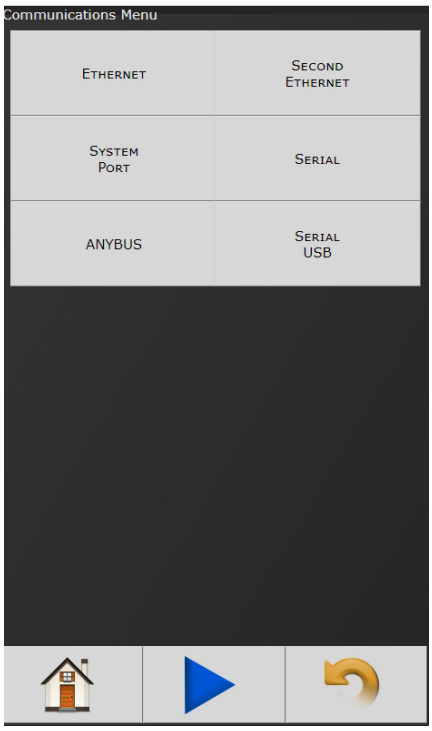
Mode:

- **Normal:** Output signal sent.
- **Timed Signal Sent:** Time entered in seconds
- **Flash Signal Sent:** Time entered in seconds

Function: See "9. Assignable I/O" on page 42 for more details on assignable functions.

Click on after appropriate changes are made.

4.5.3 Communication Interfaces



4.5.3.1 *Ethernet*

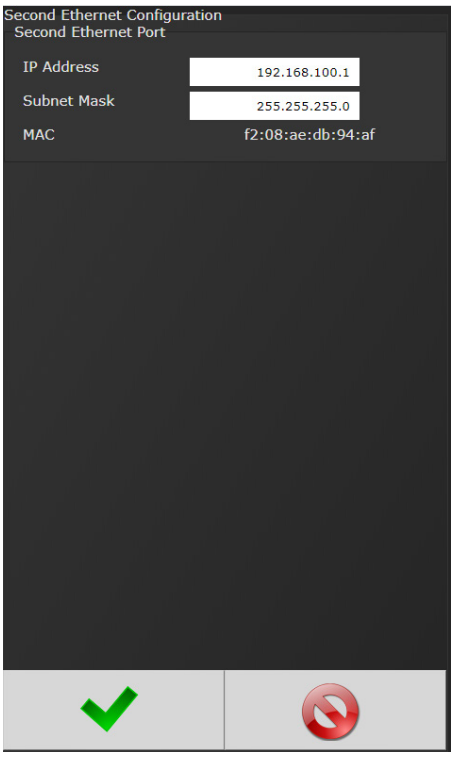
IP Address: IP address of controller's Ethernet port.

Subnet Mask: Subnet mask of the controller.

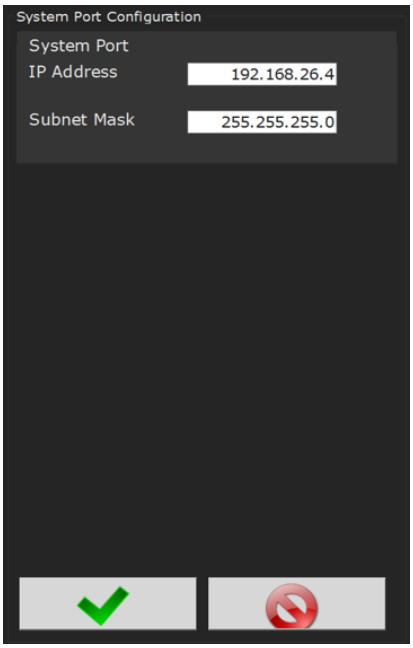
Gateway: Gateway is the IP address of the gateway computer that provides access beyond the local network.

NOTE: Consult your local System Administrator to connect the controller to your Network and assign IP addresses.

4.5.3.2 *Second Ethernet*



4.5.3.3 *System Port*

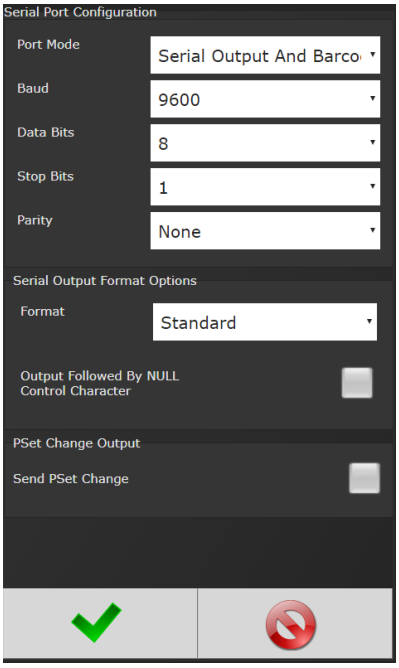


IP Address: The IP address of controller's System Port (Default is 192.168.1.4)

Subnet Mask: The Subnet Mask of controller's System Port.

NOTE: It is not recommended to change this setting.

4.5.3.4 *Serial Port*



Port Mode: The following modes are available:

- **PI Line Control:** This is customer specific. Please reference PI Line Control Document on AIMCO Website/ Product Manuals.
- **Serial Output:** A serial data string will be Output after each rundown
- **Barcode Reader:** See "5. Barcode Reader Details" on page 35 for Barcode setup.
- **Serial Output and Barcode Reader:** Select from dropdown and configure per hardware requirements
- **Open Protocol:** Select from dropdown and configure per hardware requirements
- **PFCS:** Select from dropdown and configure per hardware requirements

Baud: Serial ports can be configured for different baud rates available.

- 75, 110, 300, 1200, 2400, 4800, 9600, 19200, 38400, 57600, 115200

Data Bits / Stop Bits / Parity: Configure per hardware requirements

Serial Output Format Options: See following section "Serial Output Format Options" on page 24 for details.

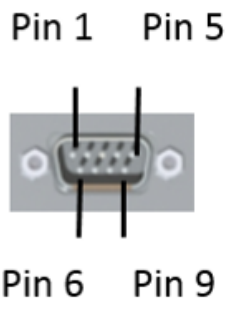
- Standard
- Standard with PSet
- UEC Serial Modified
- Profibus
- UEC Serial
- CVS String

Output Followed by Null Control Character: Adds a one-byte NULL character to the end of the serial string. Needed by systems that use the NULL character to signify the end of the string. See following section.

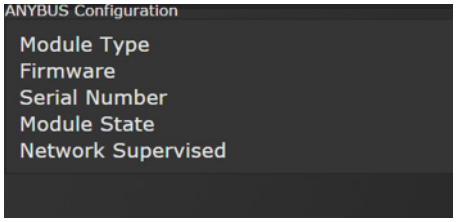
Send PSet Change: See following section.

Gen IV Serial Port Pin-out

Pin	Signal
1	
2	RX
3	TX
4	DTR
5	GND
6	
7	
8	
9	



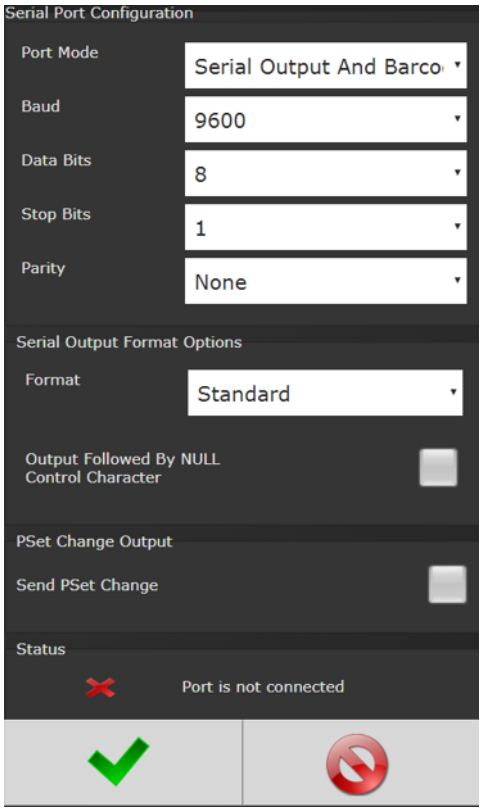
4.5.3.5 *Anybus*



Displays when the controller is AnyBus-enabled by hardware

4.5.3.6 *Serial USB*

See "4.5.3.4 Serial Port" on page 23 for reference



Serial Output Format Options

Standard Output Format:
- O P HHHHH LLLLL TTTTT P HHHHH LLLLL AAAAA CR CR NULL*
  - O: Overall Pass/Fail
    - 'P' = Pass, 'F' = Fail
  - P: Torque Pass/Fail
    - 'P' = Pass, 'F' = Fail
  - HHHHH: Torque High Limit
    - Units selected in the PSet X10
  - LLLLL: Torque Low Limit
    - Units selected in the PSet X10
  - TTTTT: Torque Result
    - Units selected in the PSet X10
  - P: Angle Pass/Fail
    - 'P' = Pass, 'F' = Fail
  - HHHHH: Angle High Limit
    - Degrees
  - LLLLL: Angle Low Limit
    - Degrees
  - AAAAA: Angle Result
    - Degrees
  - CR: Carriage return control character
  - CR: Carriage return control character
  - NULL*: Null control character (*if option is selected)

Standard Output with Carriage Return, Line Feed and PSet Format:
- O P HHHHH LLLLL TTTTT P HHHHH LLLLL AAAAA 1 CR LF NULL*
  - O: Overall Pass/Fail
    - 'P' = Pass, 'F' = Fail
  - P: Torque Pass/Fail
    - 'P' = Pass, 'F' = Fail
  - HHHHH: Torque High Limit
    - Units selected in the PSet X10
  - LLLLL: Torque Low Limit
    - Units selected in the PSet X10
  - TTTTT: Torque Result
    - Units selected in the PSet X10
  - P: Angle Pass/Fail
    - 'P' = Pass, 'F' = Fail
  - HHHHH: Angle High Limit
    - Degrees
  - LLLLL: Angle Low Limit
    - Degrees
  - AAAAA: Angle Result
    - Degrees
  - 1: PSet
    - PSet('1' – '9') for PSets 1-9, ('A' – 'Z') for PSets 10-35
  - CR: Carriage return control character
  - LF: Line feed control character
  - NULL*: Null control character (*if option is selected)

UEC Serial Modified Format (matches some Gen4 earlier versions):
- # P 1 BB TTT.T AAAA PPPP 0000 J CR NULL*
  - #: Message Start
  - P: PSet
    - PSet('1' – '9') for PSets 1-9, ('A' – 'Z') for PSets 10-35
  - 1: Spindle Number (Always 1)
  - BB: Job Bolt Count
    - Total number of accepts during the Job
  - TTT.T: Torque Result
    - Units selected in the PSet
  - AAAA: Angle Result
    - Degrees
  - PPPP: Pulse Count
  - 0000
  - J: Judgment
    - '@' = Overall Pass, 'H' = Low Torque, 'I' = High Torque, 'J' = Low Angle, 'K = High Angle, 'G' = Fault During Fastening
  - CR: Carriage return control character
  - NULL*: Null control character (*if option is selected)

Profibus Output Format:
- %CAN 1 O P HHHHH LLLLL TTTTT P HHHHH LLLLL AAAAA NAC% CR LF NULL*
  - %CAN: Message Start
  - 1: PSet
    - PSet('1' – '9') for PSets 1-9, ('A' – 'Z') for PSets 10-35
  - O: Overall Pass/Fail
    - 'P' = Pass, 'F' = Fail
  - P: Torque Pass/Fail
    - 'P' = Pass, 'F' = Fail
  - HHHHH: Torque High Limit
    - Units selected in the PSet X10
  - LLLLL: Torque Low Limit
    - Units selected in the PSet X10
  - TTTTT: Torque Result
    - Units selected in the PSet X10
  - P: Angle Pass/Fail
    - 'P' = Pass, 'F' = Fail
  - HHHHH: Angle High Limit
    - Degrees
  - LLLLL: Angle Low Limit
    - Degrees
  - AAAAA: Angle Result
    - Degrees
  - NAC%: Message End
  - CR: Carriage return control character
  - LF: Line feed control character
  - NULL*: Null control character (*if option is selected)

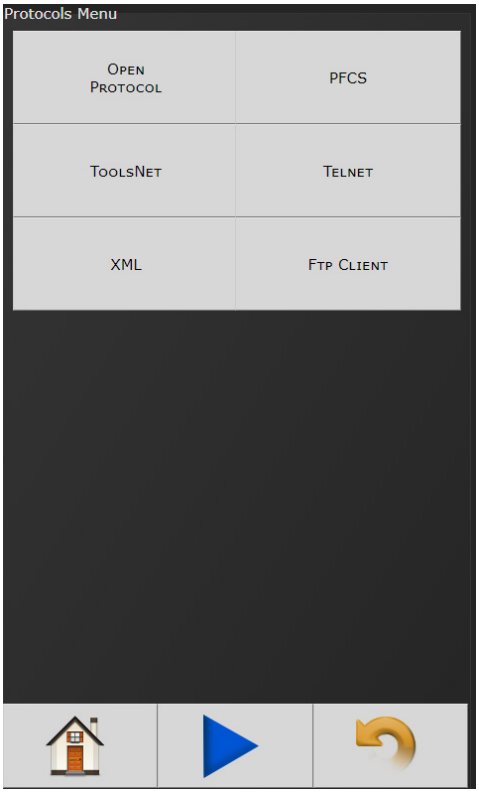
UEC Serial Format (matches UEC 4800 and Gen3):
- # 1 P BB TTT.T AAAA PPPP 0000 J CR NULL*
  - #: Message Start
  - 1: Spindle Number (Always 1)
  - P: PSet
    - PSet('1' – '9') for PSets 1-9, ('A' – 'Z') for PSets 10-35
  - BB: Job Bolt Count
    - Total number of accepts during the Job
  - TTT.T: Torque Result
    - Units selected in the PSet
  - AAAA: Angle Result
    - Degrees
  - PPPP: Pulse Count
  - 0000
  - J: Judgment
    - '@' = Overall Pass, 'H' = Low Torque, 'I' = High Torque, 'J' = Low Angle, 'K = High Angle, 'G' = Fault During Fastening
  - CR: Carriage return control character
  - NULL*: Null control character (*if option is selected)

'CSV String'
- S01,JB01, TTT.T, S, AAA.A, S, O, MM/DD/YYYY HH:MM:SS, VVV<CR><LF>
  - S01: Spindle number
  - JB01: Job number
  - TTT.T: Torque
  - S: Torque Status (A = OK, H = High, L = Low)
  - AAA.A: Angle
  - S: Angle Status (A = OK, H = High, L = Low)
  - O: Overall Status (A = OK, R = NOK)
  - MM: Month
  - DD: Day
  - YYYY: Year
  - HH: Hour
  - MM: Minute
  - SS: Second
  - VVV: 32 character barcode ID
  - <CR>: Carriage Return
  - <LF>: Line Feed

'Output Followed by NULL Character'.
- The NULL characters can be seen by using PUTTY and connecting to the controller in 'Raw' mode. Then set logging to log all output and check the log to see the NULL characters.

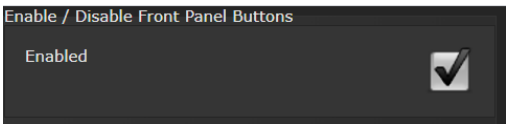
'Send PSet Change'.
- PSets up to 9 match the number, 10-35 are A-Z, greater than 35 is '*':
  - %%CAN8X%%%%CAN4YNAC%%
  - X: Last PSet
  - Y: New PSet

4.5.4 Protocols



For information about these settings, see individual protocol instructions on AIMCO's website at www.aimco-global.com

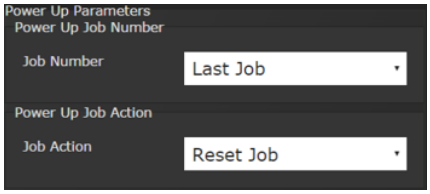
4.5.5 Front Panel Buttons



Enable/ Disable front panel buttons on controller console.

4.5.6 Power Up

Allows user several "Job" choices upon controller Power Up:



Power Up Job Number: Controller will power up on the job # selected.

- **Last Job:** When "Last job" is selected, controller will power up on last job selected prior to being Powered Down.

Power Up Job Action

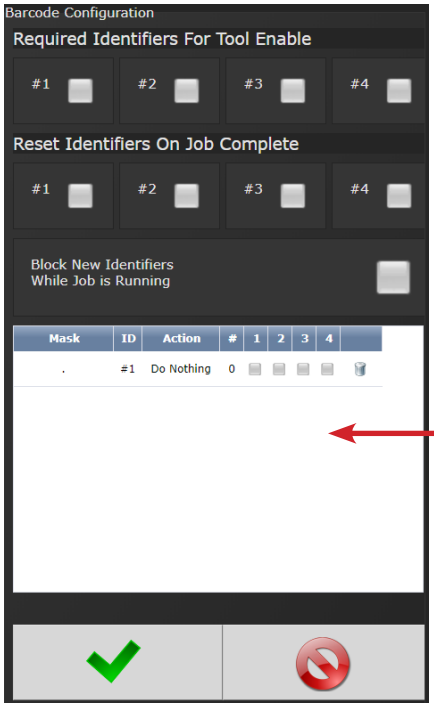
- **Reset Job:** Job will be reset when controller is Powered Up.
- **Wait for job Reset:** Controller will wait for an External Job reset command upon Power Up and will retain job information existing prior to power down.

4.5.7 Bar Code Setup

Required Identifiers for Tool Enable: Selects which four Identifiers (ID#1-4) are required to enable tool.

Reset Identifiers on Job Complete: Selects which four Identifiers (ID#1-4) to reset on a job complete. Select Identifiers by clicking on them.

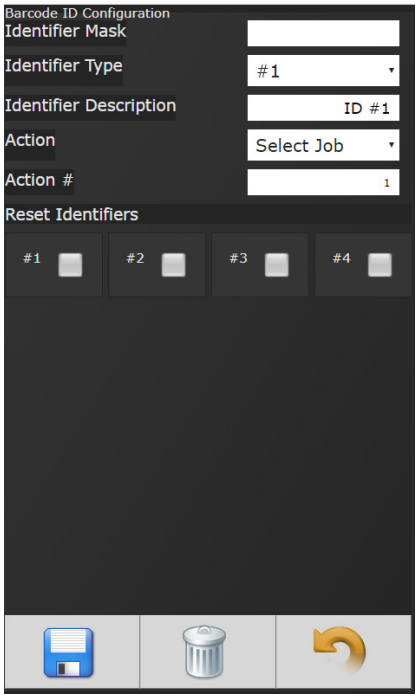
Block New Identifiers While Job is Running: Check to enable feature that ignores any barcode scanning while a JOB is in progress



Step 1: Click anywhere in body to enter the Barcode ID configuration Screen or add additional Identifiers.

Step 2: Enter appropriate information on Barcode ID Configuration Screen.

Identifier Mask: The Mask is a string used to compare the received barcode against. The received barcode must be at least as long in length as the Mask. The Mask can also contain "don't care" characters of a decimal point or period in the string. These characters are counted in the length, however, the actual received character in that position doesn't matter.



Example:

VIN#123456

Identifier Type: Identifies which identifier (ID#1-4) received barcode will be stored into.

Identifier Description: Text field can be used to give a description to each identifier type. (Example: Vehicle).

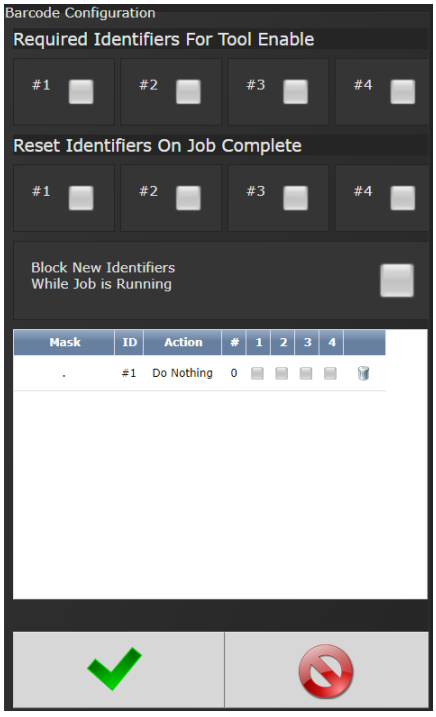
Action: Action executed by controller when barcode with a matching identifier mask is scanned. The actions are:

- Select Job (This will require a Job to be configured on the JOB page when using this option)
- Do Nothing
- Select PSet

Action#: When Select Job or Select PSet is selected, this is the number of the Job or PSet that will be selected.

Reset Identifiers: Can reset other identifiers (ID#1-4) when barcode is received. Click on identifiers to reset.

Step 3: Press  to save and re-enter completed barcode configuration screen.



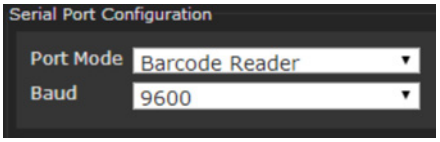
Click anywhere in body if additional identifiers are required.

Press  to save barcode configuration.

See "5. Barcode Reader Details" on page 35 for more information)

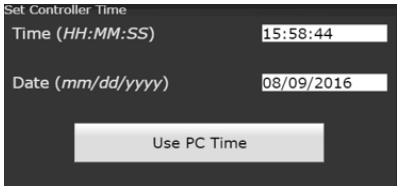
To configure Serial Port for Barcode Reader:
On Home page click Controller → Communication Interfaces → Serial

Select Barcode Reader and the correct Baud rate.



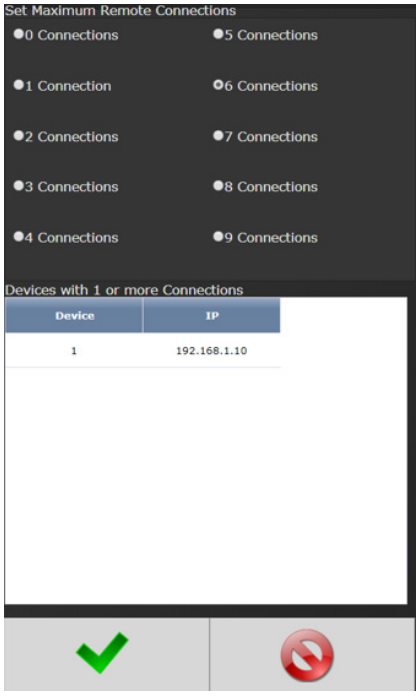
Press  to save changes.

4.5.8 Set Time



Set time and date. If connected to a PC, use PC Time to set controller time.

4.5.9 Remote Connections



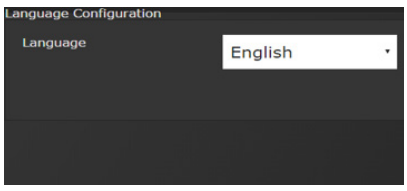
Sets number of remote browser connections to controller.

Displays the IP addresses of remote browser connections to the controller.

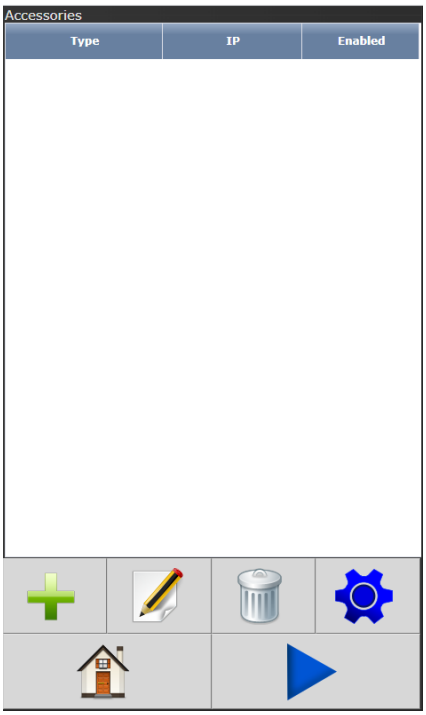
4.5.10 Languages

Select from:

- English
- Chinese
- Japanese
- Korean
- Spanish
- Portuguese

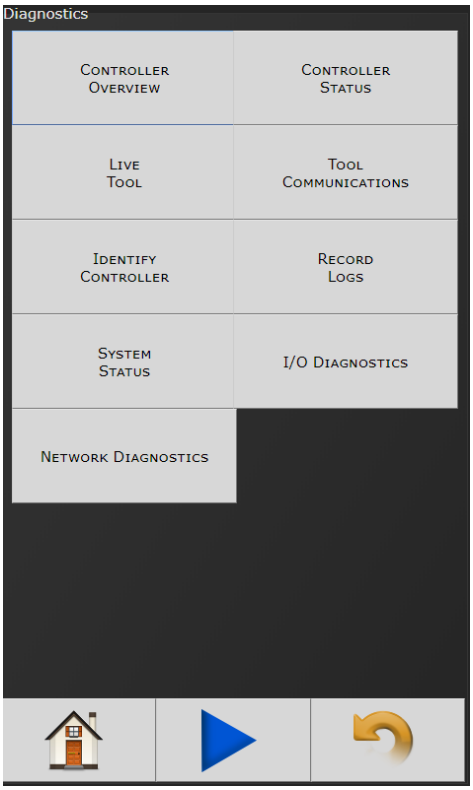


4.6 Accessories



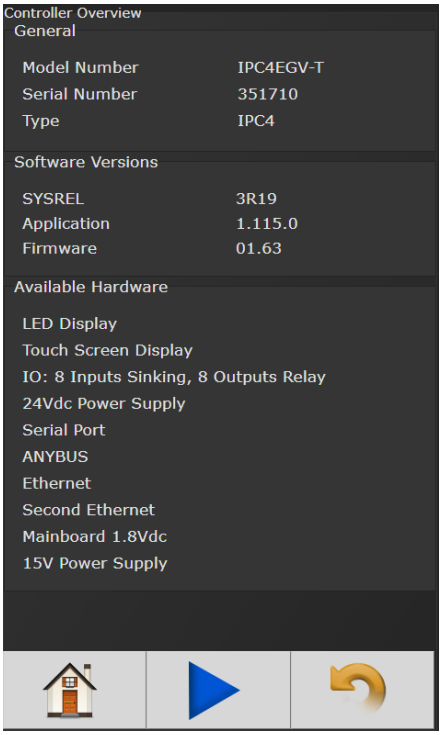
This screen shows accessories configured in the controller. New accessories can be added, edited, and deleted using the buttons at the bottom of the table. The gear icon navigates to the Accessory Scanning and Setup page.

4.7 Diagnostics



The Diagnostics menu contains all pertinent information regarding unusual behavior of the system. Detailed descriptions are given in the following sections.

4.7.1 Controller Overview



Model Number: Model Number of the controller.

Serial Number: Serial Number of the controller.

Type: Type of controller:

- **IPC**: Intelligent Electric Controller

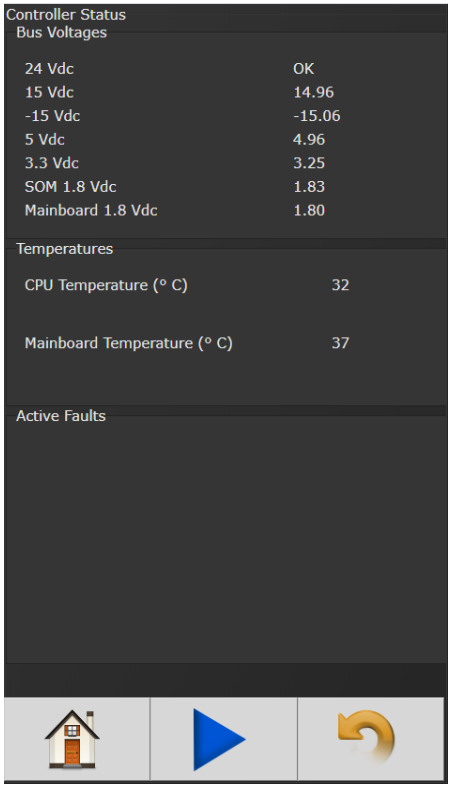
SYSREL: System Release # shown

Application: Current Application software version.

Firmware: Current Firmware software version.

Available Hardware: Available hardware on the controller.

4.7.2 Controller Status



Shows "Live" status of controller, voltages, active faults, and temperature.

Bus Voltages: Alarm icon will appear on controller console and under "Active Faults" (see below) if any of these values are out of range:

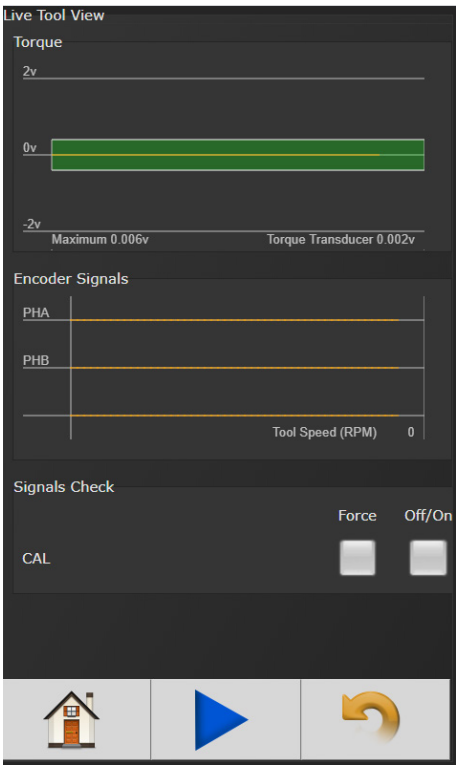
- **24 Vdc:** Represents voltage from 24V power supply. Value is reported as on or off (.0-24.0 volts) and is for external use via 24V I/O port.
- **15 Vdc and -15Vdc:** These are voltages that power the torque transducer for IAC & IPC controllers only
- **5 Vdc:** Represents voltage from 5V power supply powering controller electronics.
- **3.3 Vdc:** Represents controller electronics internal 3.3V Bus voltage.
- **SOM 1.8 Vdc:** Represents controller electronics internal 1.8V Bus voltage
- **Mainboard 1.8 Vdc:** Represents controller electronics internal 1.8V Bus voltage

CPU Temperature (° C): Represents temperature of CPU measured in Celsius.

Mainboard Temperature (° C): Represents temperature inside controller measures in Celsius.

Active Faults: Any tool/ controller faults will be shown in this area.

4.7.3 Live Tool Features



Torque: Shows a live view of tool transducer in volts. Voltage will be approximately 2.0 volts (± 0.005 Vdc) when tool is at rest and torque is zero (verify the voltage is within the green zone in the graph).

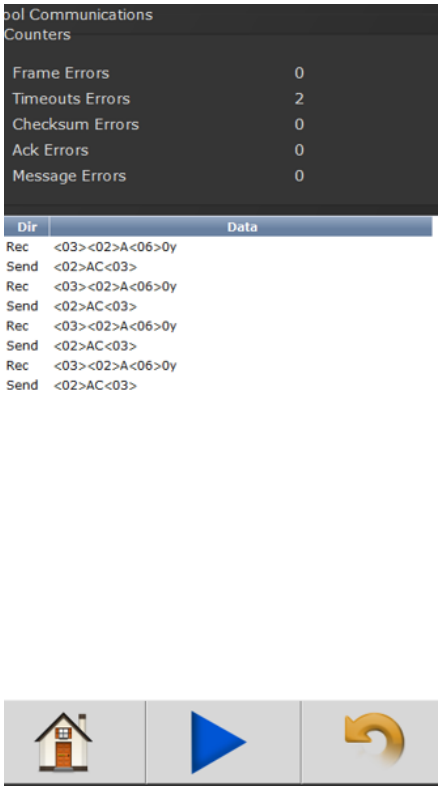
During a rundown, tool transducer voltage increases as torque increases.

Encoder Signals will be monitored along with tool RPM. (Only applies for tools with Angle Sensing capability 'Resolver')

Signals Check: Encoders sensors can be monitored for function and reliability

CAL: A CAL signals check can also be toggled Forcing the cal check will drive the torque transducer voltage to near 2.0V if the tool is operating correctly.

4.7.4 Tool Communications

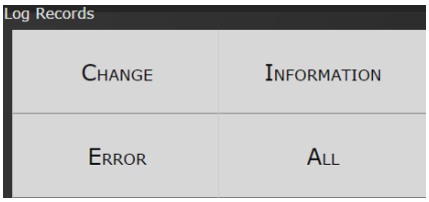


Access this screen to view the communications between the tool and controller. Data should be continually streaming if the system is working normally. This can be used to identify issues with tool communication. If no data is being sent between the tool and controller then there may be a hardware problem. These logs can be saved for troubleshooting purposes.

4.7.5 Identify Controller

'Identify Controller' will cause lights on controller and tool to flash making the system easy to locate. This is especially helpful when programming is being done and multiple controllers are being used in close proximity to each other.

4.7.6 Record Logs



Logs information describing usage of controller and tools that have been used with that controller. ***4.7.6.1***

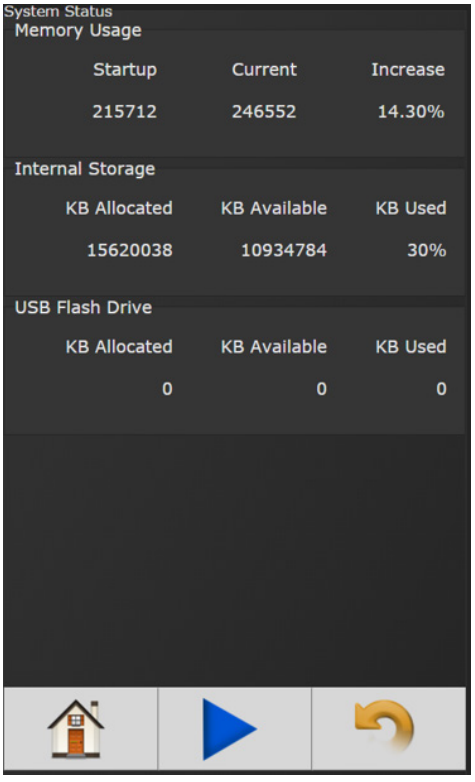
Change Log
Log displays changes made to tool or controller.

4.7.6.2 Information Log
Log displays all information entries.

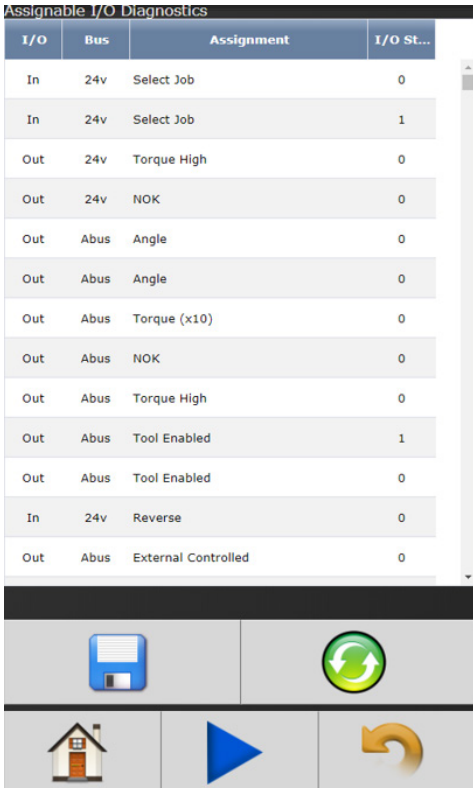
4.7.6.3 Error Log
Log displays ONLY Error Entries.

4.7.6.4 All
Displays all Changes, Information and Error entries.

4.7.7 System Status



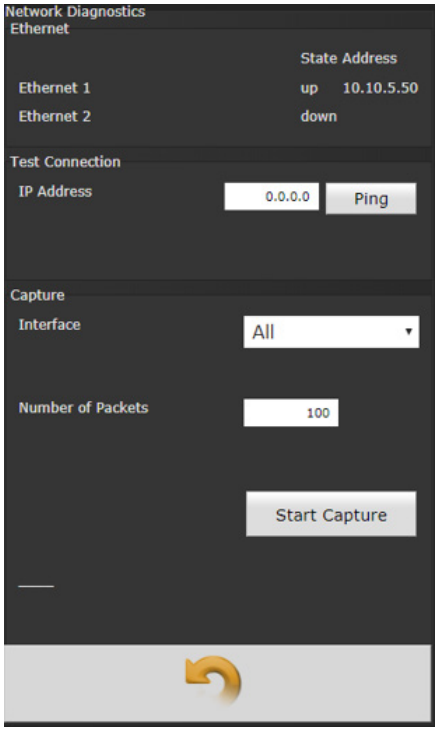
4.7.8 I/O Diagnostics



This screen shows a record of the last changes in state of all the assigned I/O that are active. Record can be saved to diagnose I/O functionality

4.7.9 Network Diagnostics

Network Diagnostics can be useful in troubleshooting Ethernet communication issues



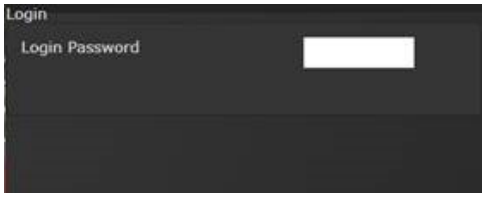
Ethernet: Shows if the Ethernet port is physically connected and if the hardware is operational.

Test Connection: Provides a way to check the ethernet connection to other devices on the same network.

Capture: Captures and saves the ethernet traffic for evaluation

4.8 Login

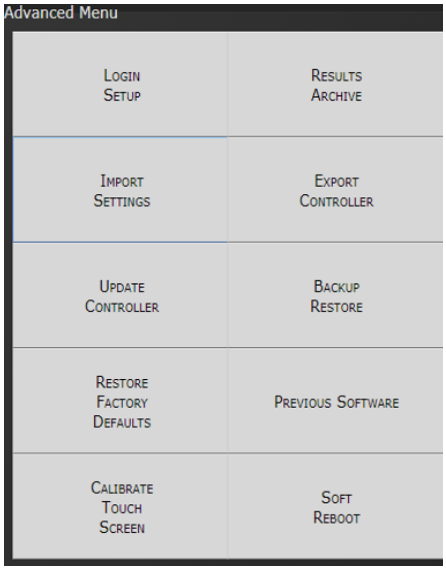
When a password is required it can be entered in this screen.



Three levels of access to the controller are available:

- **Operator:** Run/Login screens available.
- **Technician:** Run/PSet/Job/Diagnostics and Login screens available.
- **Administrator:** All screens available.

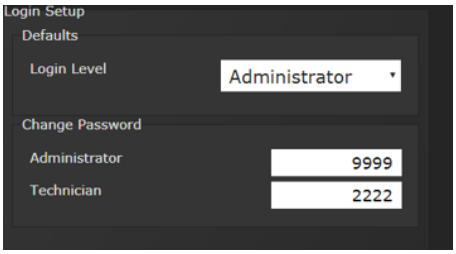
4.9 Advanced



The 'Advanced' menu handles complex settings within the controller. Detailed descriptions are given in the following sections.

4.9.1 Login Setup

This screen allows the user to select the default Login level upon controller start up.



- **Operator**
- **Technician**
- **Administrator**

4.9.2 Results Archive

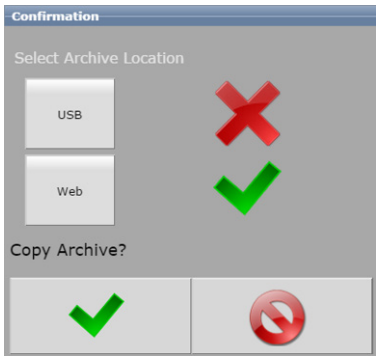
Select a file and press 

Approximately one million rundowns can be stored. Twenty files with approximately 50,000 rundowns are maintained at a time. The user can, at any time, save the runs to either a USB stick or to the Web as a USV file imported directly into an Excel spreadsheet.

Using the touchscreen console, you can select multiple files to save.

Using the web option, you can select one of these files at a time to save (web option is default).

Select either USB or Web Archive location



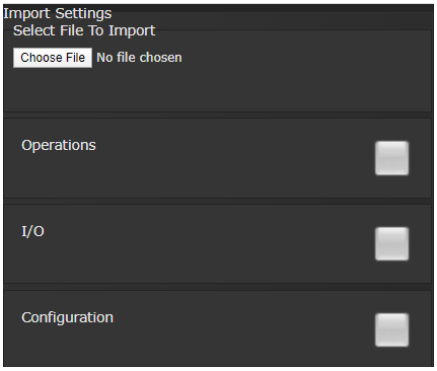
Example of Saved Excel File

Rundown	Job Num	Job Name	Sequence	Bolt count	Status	Date	Time	Torque	Status	Angle	Status	PSet Num	PSet Name	Tool Mode	Tool Serial	Id1 (ID #1	Id2 (ID #2	Id3 (ID #3	Id4 (ID #4)
2068	0		0	0	P	########	11:13:42	5.08	P	480	--	1			0				
2069	0		0	0	P	########	11:13:49	5.054	P	535	--	1			0				
2070	0		0	0	P	########	11:13:50	5.002	P	450	--	1			0				
2071	0		0	0	P	########	11:13:52	5.013	P	595	--	1			0				
2072	0		0	0	P	########	11:13:53	5.085	P	495	--	1			0				
2073	0		0	0	P	########	11:13:54	5.1	P	440	--	1			0				
2074	0		0	0	P	########	11:13:56	5.089	P	575	--	1			0				

4.9.3 Import Settings

This allows the user to download any previously saved settings onto the controller (refer to 'Export Controller' for help with saving data).

1. Plug the USB with an export file into any port on the controller.
2. From the Home screen, navigate to Advanced → Import Settings.
3. Select the settings to be checking the corresponding box ☑



Operations: This includes PSets and Jobs.

I/O: This includes I/O settings for the local I/O, Anybus, Modbus, and EtherNet/IP.

Configuration: This includes all settings of the controller except I/O, Master Spindle, Rundowns, PSets or Jobs.

Spindle: This includes any Master Spindle setup (i.e. number of spindles, slave IP addresses, etc).

4. Press ✔ to accept the changes.
5. Press ✔ to proceed.
6. Press ✔ when the import is complete and the controller will restart.

Import settings that were exported from another controller via a USB flash drive. Use this to quickly apply the same settings across several controllers. For example, it is common to have multiple controllers with the same I/O configuration. Set up one controller with the correct I/O configuration and export the controller from Advanced → Export Controller. Now the I/O settings can be imported using this screen.

NOTE: Setting can only be imported from controllers running the same version of software.

4.9.4 Export Controller

This allows the user to save Configuration, Operations, I/O, and Spindle settings onto a USB flash drive.

1. Plug a USB into any port on the controller.
2. From the Home screen, navigate to Advanced → Export Controller.
3. Press ✔ to continue, and the controller will begin the export process.
4. Press ✔ to complete the export.

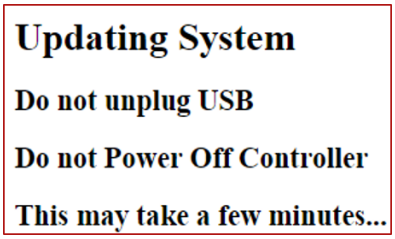
4.9.5 Update Controller

NOTE: Updated firmware versions will typically be sent via email zip file. Always save PSet and IP address information before upgrading controller.

Upgrading the AIMCO Gen IV Controller
Using the TouchScreen or a System Port browser session, navigate to the 'Advanced' menu. Click 'Update Controller' and select the latest release.

Click the green checkmark when ready.

After the controller restarts, the user should see following messages



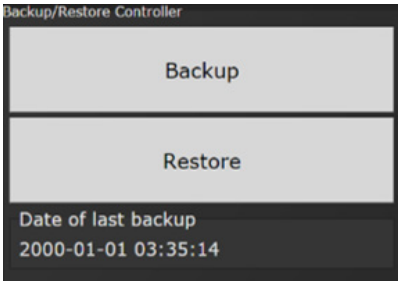
Controller Upgrade Notification

When the controller has finished, navigate to Diagnostics → Controller Overview to view any changes to the 'Software Versions'. Any system settings (Ethernet IP address, PSets, Jobs, etc.) will remain unchanged.

4.9.6 Backup Restore

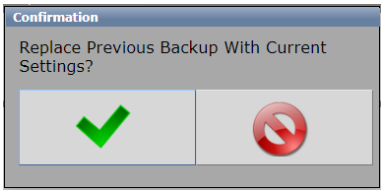
The Backup function allows the user to create an image of the controller software/firmware including all Configurations, Operations, I/O, and Spindle settings. This is used to create a point in which the controller can restore to if the need arises. In that case, the Restore function would be used.

1. From the Home screen, navigate to Advanced → Backup Restore.



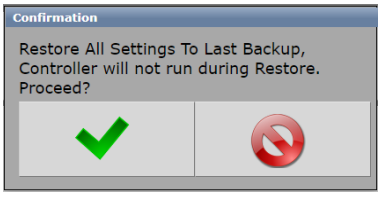
2. Press Backup to initialize the backup process.

3. Press ✔ to replace previous backup with current system, the backup process will begin.



4. Press **Restore** to initialize the restore process.

5. Press ✔ to restore all settings and firmware to last backup, the restore process will begin.

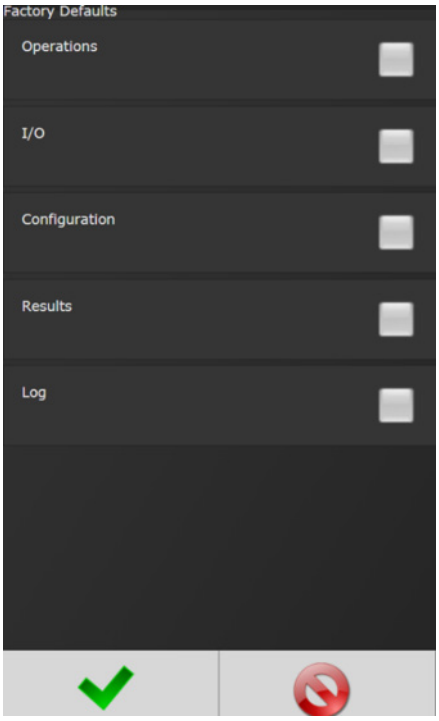


6. The controller will restart when finished.

4.9.7 Restore Factory Defaults

This allows the user to reset the controller's parameters to factory settings

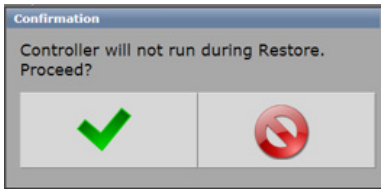
1. From the Home screen, navigate to Advanced → Restore Factory Defaults.
2. Select the settings to be changed and accept ✔



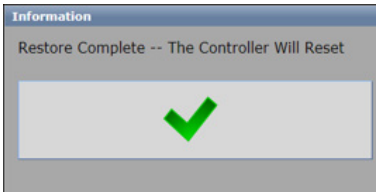
- **Operations:** This includes PSets and Jobs.
- **I/O:** This includes I/O settings for the local I/O, Anybus, Modbus, and EtherNet/IP.
- **Configuration:** This includes all settings of the controller except I/O, Master Spindle, Rundowns, PSets or Jobs.
- **Results:** This includes all rundown data /information
- **Log:** This includes the Change, Information, Error, and Combined logs.

3. Press ✔ to accept the changes.

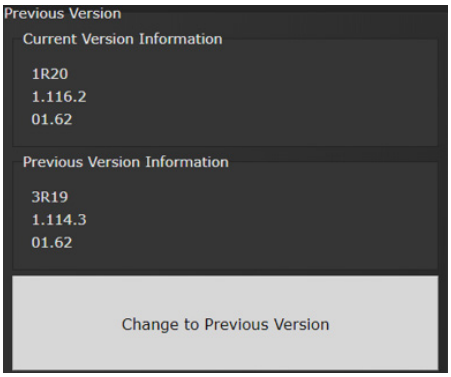
4. Press ✔ to proceed.



5. Press ✔ when the calibration is complete, the controller will restart.



4.9.8 Previous Software



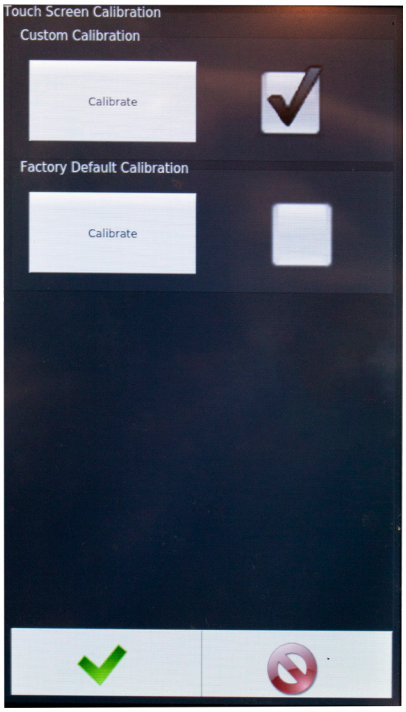
The 'Previous Software' page enables users to change the software to an alternate version. When the controller is updated, the previous version will be retained to easily revert versions. Settings are not affected. Any changes to settings are retained when changing to an alternate version. The screen shows the current version along with the version information of the alternate version.

This feature is only available for versions 3R19 going forward. It is not possible to revert to a release earlier than 3R19.

4.9.9 Calibrate Touch Screen

Custom and Factory default calibration are available on the controller console.

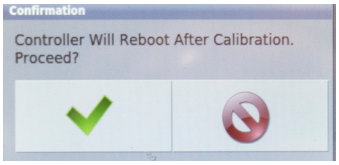
1. From the Home screen, navigate to Advanced → Calibrate Touch Screen.
2. Press ✔ to disable the tool.
3. Select the desired calibration



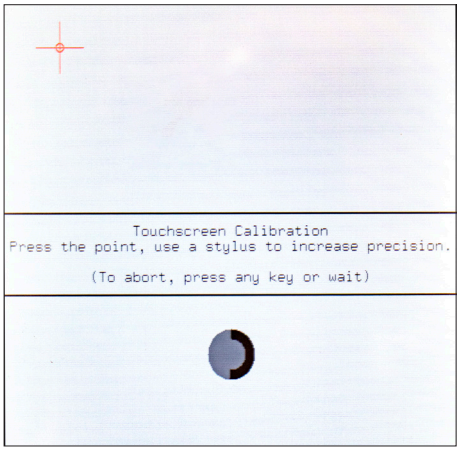
Custom Calibration: This allows the user to create a custom calibration setting for the touch screen.

Factory Default Calibration: This calibrates the touchscreen to the factory defaults.

4. Press ✔ to accept the selection.
5. Press ✔ to proceed.



In the case of custom calibration, a screen will appear with instructions on how to increase precision.



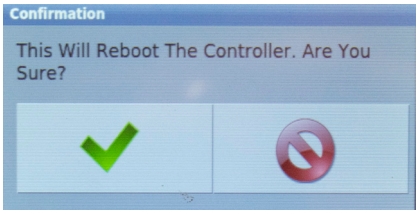
6. Press ✔ when the calibration is complete, the controller will restart.

NOTE: The controller may need to be reset before the custom calibration is possible.

4.9.10 Soft Reboot

Restart the controller without turning the power off.

1. From the Home screen, navigate to Advanced → Soft Reboot.
2. Press ✔ to proceed, the controller will restart.



5. Barcode Reader Details

The Gen IV controller supports the following barcode reader functionality:

- Support up to four identifiers.
- Each rundown result can be associated with up to four identifiers.
- Identifier(s) can be used to select a parameter set or a job.
- Display identifier(s) on controller.
- Ability to lock-out tool until correct identifier(s) is entered.
- Ability to block barcode reads while a job is in progress.
- Barcode reads (identifiers) can come from any or all the following sources:
  - Serial barcode reader
  - Open protocol
  - Fieldbus network
  - Telnet port

Solution
Regardless of the source (serial barcode reader, telnet, fieldbus, or protocol) each new string is passed through the same process:

- All four identifiers are reset to an empty string on power-up.
- Each received barcode is processed through a Barcode Match Table to look for a match, if one is found the barcode is accepted.
- Each fastening will then be associated with the received barcode(s) until a new one is received or they are reset.

Parameters
The parameters that pertain to the processing of barcode strings:

- The Barcode Match Table is used to identify the newly received barcode string.
- Which of the four Identifiers (ID#1-4) are required to enable the tool?
- Which of the four Identifiers (ID#1-4) to reset on a job complete?
- Parameter to disable all barcode reads while a job is in progress. If set, barcode reads will be disabled after the first fastener is ran until job is complete.

Barcode Match Table
The Barcode Match Table is used to identify which barcode has been received. The controller can have up to 99 entries (rows) in the table. Each entry has actions that will be performed when a matching barcode is received. The table is searched from top to bottom in an attempt to find a matching barcode. If none are found, the barcode is ignored.

Mask
The Mask is a string used to compare against the received barcode. The received barcode must be at least as long in length as the Mask. The Mask can also contain "don't care" characters of a decimal point or period in the string. These "don't care" characters are counted in the length but the actual received character in that position doesn't matter.

Identifier Type
The "Identifier Type" field identifies which identifier (ID#1-4) the received barcode will be stored in.

Action
Action can be one of the following:
- None
- Select PS#1-256
- Select Job#1-20

Reset ID
The "Reset ID" has the ability to reset other identifiers (ID#1-4) when barcode is received.

Examples:

Operator Scans
When a vehicle enters the station, the operator scans the VIN. The controller selects the correct job number and enables the tool. Each fastener will be identified with this VIN stored locally, and/or sent to a server for storage. The job settings will disable the tool when the job is complete.

Setup
In this example, there are three possible vehicle types each with its own job. The barcode scan will select the correct job (enabling the tool) and the scan will be stored into ID#1.

				Reset ID			
Mask	ID type	Action		ID#1	ID#2	ID#3	ID#4
"VIN.....7..."	ID#1	Select Job#	1	No	No	No	No
"VIN.....8..."	ID#2	Select Job#	2	No	No	No	No
"VIN.....9..."	ID#3	Select Job#	3	No	No	No	No

The tool enable/disable will be controlled by the job settings; the correct job will be selected by the barcode scan. The "ID Required to Enable the Tool" feature does not need to be utilized.

Required Identifiers for Tool Enable			
ID#1	**ID#2**	**ID#3**	**ID#4**
No	No	No	No

These settings are irrelevant since the only way to enable the tool is with a new job and the only way to select a new job is to scan a new barcode.

Reset Identifiers on Job Complete			
ID#1	**ID#2**	**ID#3**	**ID#4**
Yes	No	No	No

Examples
This is what the 'Operator Scans' example looks like once set up in the Barcode Configuration Screen (see "4.5.7 Bar Code Setup" on page 25).

Airbag Install
The customer wants to track the serial number of each airbag being installed, as well as the operator installing it. When the operator reports to the station, they will scan their employee ID. When the vehicle comes into the station, the operator scans the VIN of the vehicle and the serial number of the airbag. Once all three scans are received, the tool is enabled. Once the correct number of fasteners are installed, the tool is disabled by the job settings. From that point, the operator only needs to scan the vehicle and the airbag to enable the tool.

Setup
We will assign the employee ID to ID#1, the vehicle VIN to ID#2, and the airbag serial number to ID#3. Scanning a new employee ID will reset the other IDs and force a scan of the vehicle VIN and airbag serial number. The scan of the vehicle VIN will also select the correct job number.

Mask	ID type	Action		Reset ID ID#1	ID#2	ID#3	ID#4
"EMP…."	ID#1	None		No	Yes	Yes	No
"VIN……."	ID#2	Select Job#	1	No	No	No	No
"SN……."	ID#3	None		No	No	No	No

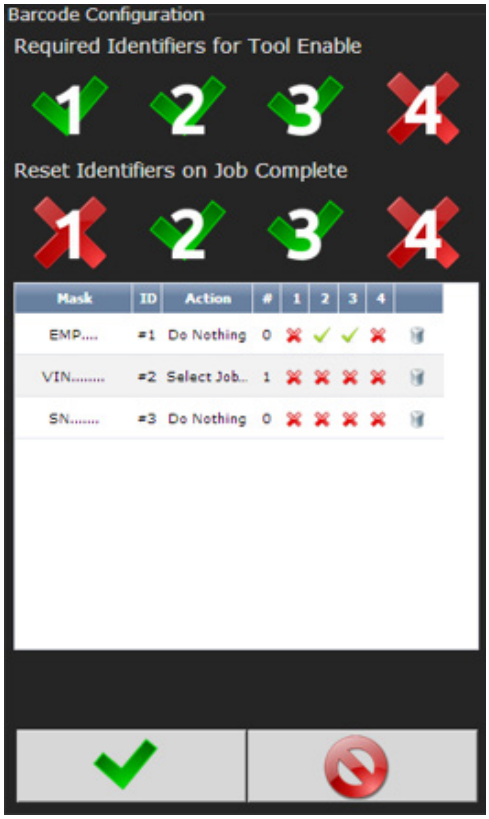
Once all three scans are received, the tool will be enabled.

Required Identifiers for Tool Enable			
ID#1	**ID#2**	**ID#3**	**ID#4**
Yes	Yes	Yes	No

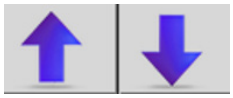
When job is complete, the vehicle VIN will be reset and the airbag serial number, but not the employee ID; this way subsequent vehicles will only require a VIN and S/N to enable tool.

Reset Identifiers on Job Complete			
ID#1	**ID#2**	**ID#3**	**ID#4**
No	Yes	Yes	No

This is what the Airbag Install example looks like set up in the Barcode Configuration Screen (see "4.5.7 Bar Code Setup" on page 25.

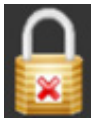


6. Icons Defined

Icon	Description	Function	Where Used
	Home Navigation Button	Navigate to the main menu ("HOME") screen.	All screens except for edit screens.
	Run Navigation Button	Navigate to the Run Screen.	All screens except for edit screens.
	Run Screen Select Buttons	Switch between the different run screen pages.	Run Screen
	Go Back Button	Navigate to one menu level back.	All screens except for edit screens.
	Accept Changes Button	Accept the changes made and return to the parent screen.	Edit screens
	Cancel Changes Button	Reject the changes made and return to the parent screen.	Edit screens
	Add New Button	Add a new item (Pset, Stage, Job, and other).	PSet and Job edit screens.
	Edit Button	Edit selected Item.	PSet and Job edit screens.
	Move Up and Down Buttons	Move selected item up or down in the sequence order.	PSet and Job edit screens.
	Copy Button	Copy selected Items	PSet, Job, and other edit screens.
	Delete Button	Remove or un-assign selected items.	Edit and list view screens.
	Filter Button	Filter Items in a list or table.	List view screens
	Save Button	Save selected item to file.	List view screens
	Disassembly	A disassembly event has been detected.	Run Screen

6.1 Stop Codes

If a Stop condition is detected that prevents the tool from running, a code will appear on the LED display. Any active stop conditions are also displayed on the RUN screen.

Code	Icon	Description
IO		Stopped or Disabled from Physical 24 volt IO input
ABUS		Stopped or Disabled from ANYBUS
MODB		Stopped or Disabled from Modbus
EIP		Stopped or Disabled from Ethernet IP
RTU		Stopped or Disabled from Modbus RTU
OP		Stopped or Disabled from Open Protocol
OP		Lost Open Protocol Connection
REV		Disassembly Disabled
ARM		Tool Requires Arming – MFB button configured to enable the tool to run.
JOB		Job Sequence Complete
JOB		Job Complete
JOB		XML Count Complete
LOR		Locked on Reject

Code	Icon	Description
BRCD		Bar Code ID scan required to enable tool
SRVC		Tool Disabled For Service - Tool service or calibration interval has expired
INVP		Invalid PSet - Parameter set number for a non-existent Pset has been selected to run. Most likely via one of the following methods: ◦ Job ◦ MFB ◦ I/O
INVP		PSet outside of Job - Parameter set number outside of the job has been selected. Most likely via one of the following methods: ◦ MFB ◦ I/O
INVJ		Invalid Job - Job number for a non-existent Job has been selected to run. Most likely via one of the following methods: ◦ MFB ◦ I/O
PSET		PSet Mismatch
SPND		Spindle Not Configured – Spindle selected to run from a Multi-Spindle Job has not been configured
NET		XML Disconnected
XML		Stop from XML
NOK		XML Max Rejects Exceeded
FLT		Controller Fault - Error has been detected. See fault code list for details

7. Error Codes

If an error condition is detected that prevents the tool from running, a fault code will appear on the LED display. Any active faults are also displayed on GUI RUN screen. Fault history can be viewed in the Controller Error Log.

Gen4 Common Hardware Fault Codes

Code	Fault Type	Description	Possible Causes
FH17	1.8vdc MB out of tolerance	Main board 1.8 bus voltage exceeds electrical limits	• Faulty Controller main board or other Controller electronics
FH18	1.8vdc SOM out of tolerance	System on Module 1.8 bus voltage exceeds electrical limits	• Faulty Controller main board or other Controller electronics
FH19	3.3vdc out of tolerance	Main board 3.3 bus voltage exceeds electrical limits	• Faulty Controller main board or other Controller electronics
FH20	5vdc out of tolerance	5 Volt bus voltage out of range	• Faulty power supply or wiring • Faulty Controller main board or other Controller electronics
FH21	9vdc out of tolerance	9 Volt bus voltage out of range	• Faulty power supply or wiring • Faulty Controller main board or other Controller electronics • Faulty tool cable • Faulty tool electronics or wiring
FH22	24 volt level low	24 Volt I/O power not detected	• Faulty power supply or wiring • Short or other problem with external connections to the 24Volt I/O port.
FH23	Controller temp high	Controller's internal temperature exceeds limit	• Ambient air temperature exceeds rating of Controller
FH24	+15vdc out of tolerance	+15 Volt bus voltage out of range	• Faulty power supply or wiring • Faulty Controller main board or other Controller electronics • Faulty tool cable • Faulty tool electronics or wiring
FH25	–15vdc out of tolerance	–15 Volt bus voltage out of range	• Faulty power supply or wiring • Faulty Controller main board or other Controller electronics • Faulty tool cable • Faulty tool electronics or wiring
FH32	Processor Fault	RTOS processor not communicating with the Application processor	• Faulty mainboard electronics • RTOS processor firmware corrupted or not loaded • Faulty SOM board or connector

IPC (URYU Electric Pulse Tool) Specific Fault Codes

CODE	Fault Type	Description	Possible Causes
FP01	Torque signal out of Range	Tool torque signal voltage is beyond electrical limits	• Tool not connected • Faulty tool cable • Faulty transducer • Transducer electronics not calibrated • Faulty tool/controller electronics or wiring
FP02	Torque tare value out of range	Tool torque signal no load voltage is out of range	• Faulty tool cable • Transducer electronics significantly out of calibration • Faulty transducer
FP03	Torque Cal signal out of Range	Tool does not respond to the full scale voltage CAL single	• Tool not connected • Faulty tool cable • Faulty transducer • Transducer electronics not calibrated • Faulty tool/controller electronics or wiring
FP04	Tool Not Connected	Tool communication timeout	• Tool not connected • Faulty tool cable • Faulty tool electronics or wiring

8. 24 Volt I/O

Port Pinout and Diagrams

An I/O wiring adapter kit is available (Part #**27348**) from AIMCO to make connection to I/O port on the controller easier. Contact your AIMCO Sales Representative for ordering information. Toll Free: 1-800-852-1368.

Pin #	Function	Default Assignment
1	Output 1	NOK/Timed
2	Output 2	OK
3	Output 3	In Cycle
4	Output 4	Torque High
5	Outputs 1-4 common	
6	Input 1	Start
7	Input 2	Reverse
8	Input 3	Disable Tool
9	Input 4	PSet Bit 1
10	Input 5	PSet Bit 2
11	Input 6	PSet Bit 3
12	Input 7	Reset Job
13	Input 8	Stop
14	Output 5	Torque Low
15	Output 6	Angle High
16	Output 7	Angle Low
17	Output 8	Job Complete
18	Outputs 5-8 common	
19	N/C	
20	N/C	
21	24 V Return	
22	24 V Return	
23	+24 Vdc	
24	+24 Vdc	
25	+24 Vdc	

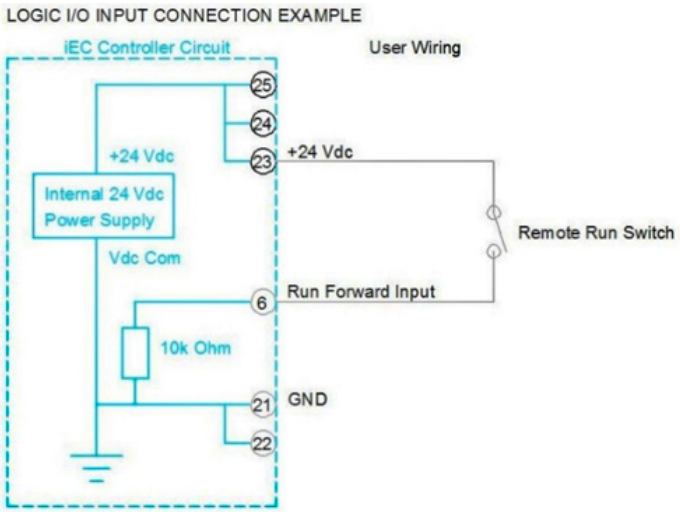
NOTE: The Default Assignments in Table above are factory defaults and can be changed. See "9. Assignable I/O" on page 42.

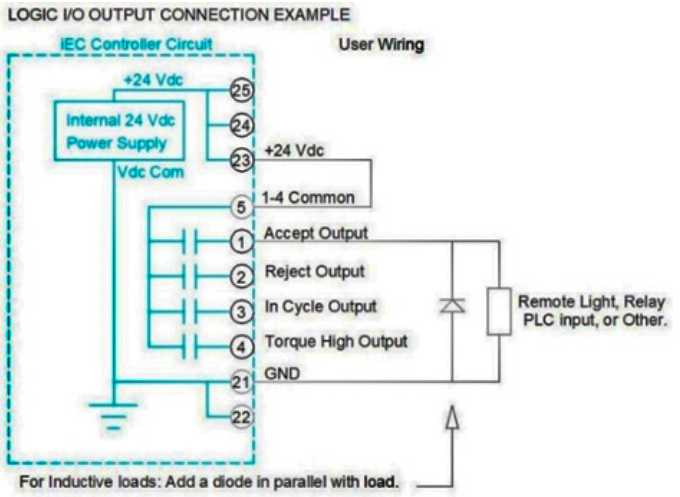
24 Volt I/O Connections

Turn off system before connecting to the LOGIC I/O port. There may be risk of damaging the controller.

- **24Vdc Supply:** The internal 24Vdc power can supply up to 1 amp.
- **Inputs:** Inputs are a sinking configuration with the common connected to the ground pins. 24Vdc is logic ON and 0Vdc is logic OFF.
- **Outputs:** Outputs are normally open relay contacts. The relays are rated for 24Vdc, 1 amp.

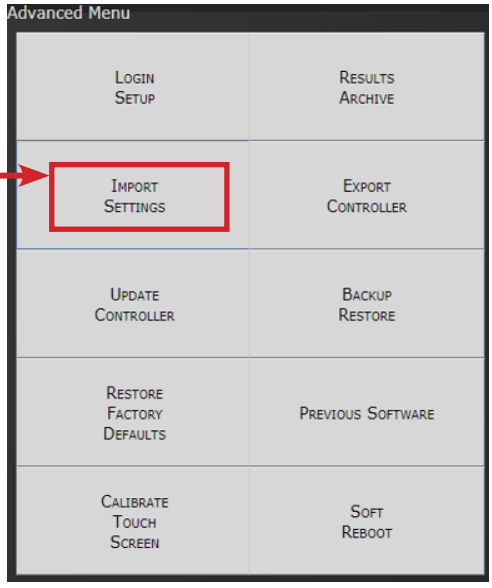
NOTE: If Outputs are driving an inductive load, such as a solenoid or large relay, it is recommended to add a diode in parallel with the load to prevent voltage surges.



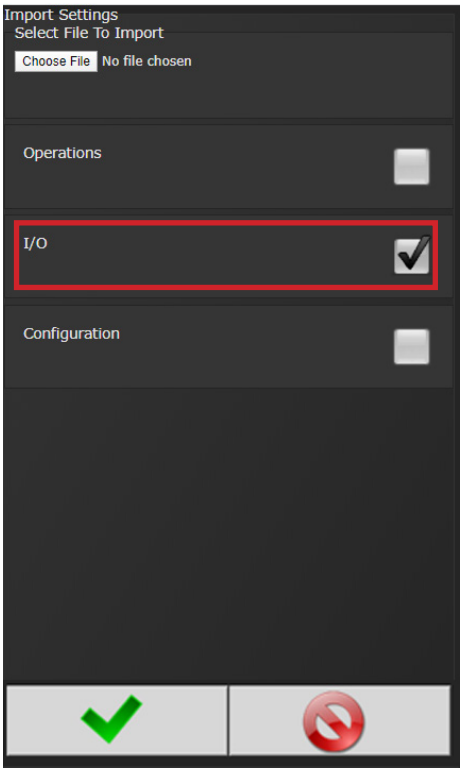


Importing I/O on an iPC4
These instructions detail how to import IO into an iPC4 controller via the system port to modify the Anybus outputs.

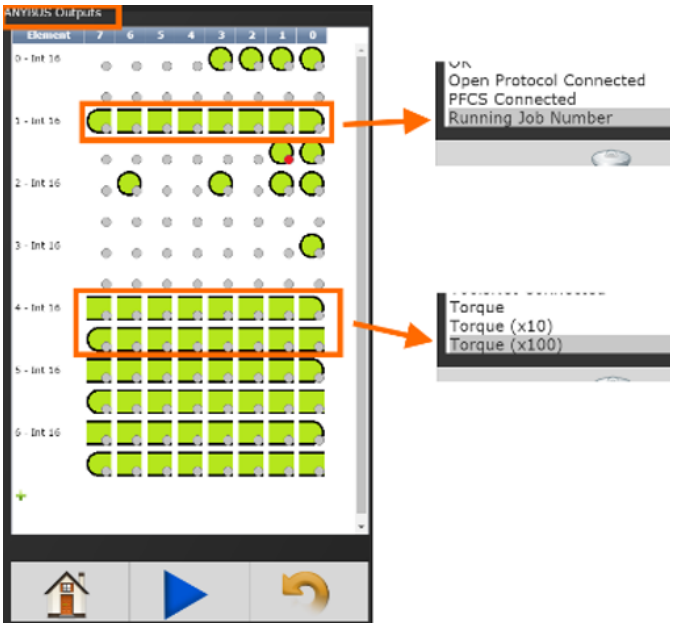
1. Power on the controller
2. Insert the USB stick into a USB port
3. Connect to the controller via system port and web browser (default address 192.168.1.4)
4. Navigate to Advanced → Import Settings



5. Choose file and select **ONLY I/O**



6. Click OK
7. Click OK in the Confirmation dialog box
8. The controller will restart
9. Verify the Anybus outputs.
    a. Navigate to Controller → IO → Anybus Outputs
    b. Click on the first row of element #1 and verify it is set as 'Running Job Number', Bit 0, Bits 8, Start at 0.
    c. Click on element #4 and verify it is set as "Torque (x100)", Bit 0, Bits 16



9. Assignable I/O

The Gen IV controller supports assignable I/O.

Buses
The controller is divided up into buses. Each bus has a set of inputs and a set of outputs. Currently the controller supports the following buses.

Bus Number	Bus
1	Physical I/O
2	Fieldbus (Anybus module) I/O
3	Modbus TCP
4	Ethernet/IP

All assignments have a bus, element, and bit configuration to define its location in the system. The bus value needs to be set from the list above. The element and bit define the location in the bus. The first element on the bus is 0 and goes up the last legal element for the given bus. The bits in each element is referenced from 0(LSB) to 31(MSB).

Inputs
All input assignments have a Bus, Element, and Bit configuration to define its location in the system. Along with the basic configuration many also have other configuration(s) that allow its behavior to be modified to suit the application.

	Supported Feature						Controllers				
	Bus	Element	Bit 0-31	Polarity N.O./N.C.	Width	Offset	iEC	iAC	iPC	iBC	iBC-Z
Do Nothing	√	√	√				√	√	√	√	√
Start	√	√	√	√			√				
Stop	√	√	√	√			√	√	√	√	
Reverse	√	√	√	√			√				
Disable	√	√	√	√			√	√	√		
Reset Job	√	√	√	√			√	√	√	√	√
Select PSet	√	√	√		√	√	√	√	√	√	
Select Job	√	√	√		√	√	√	√	√	√	√
Select Job Sequence	√	√	√		√	√	√	√	√	√	√
Disable Assembly	√	√	√	√			√				
Set ID	√	√	√		√		√	√	√	√	√
Set ID (word swap)	√	√	√		√		√	√	√	√	√
Set Date/Time	√	√	√		√		√	√	√	√	√
Set Date/Time (word swap)	√	√	√		√		√	√	√	√	√
Verify PSet	√	√	√		√	√	√	√	√	√	√
Clear Results	√	√	√	√			√	√	√	√	√
Log Change	√	√	√		√	√	√	√	√	√	√
Decrement Batch	√	√	√	√			√	√	√	√	√
Increment Batch	√	√	√	√			√	√	√	√	√
Click Wrench	√	√	√	√			√	√	√	√	√
Bypass Stops	√	√	√	√			√	√	√	√	√
Verify Job Sequence	√	√	√		√	√	√	√	√	√	√
ASCII ID	√						√	√	√	√	√
Abort Job	√	√	√	√			√	√	√	√	
Remote Start	√	√	√	√			√				
Remove Lock on Reject	√	√	√	√			√	√	√	√	

Polarity
When the polarity is set to N.O. the input is considered active high (24vdc for physical inputs and logic 1 for all network type buses). When the polarity is set to N.C. the input is considered active low (0vdc for physical inputs and logic 0 for all network type buses).

Width and Offset
For multiple bit inputs (for example "Select PSet") the width variable defines the number of bits the assignment will read for its input. This allows the input size to be restricted to a few bits saving space for other assignments.

The offset variable allows a fixed value to be added to the read value.

For example to use bits 4 & 5 of the physical inputs to select parameter sets 1-4 the assignment would look like…

Select PSet		
Bus	1	For the physical bus
Element	0	For the first element on the bus
Bit	4	For the starting bit location
Width	2	To span the two bits 4 & 5
Offset	1	Adding 1 to the read input value so we get… Binary 00 = 1 Binary 01 = 2 Binary 10 = 3 Binary 11 = 4

Input Assignments

Do Nothing Supported Feature

Bus	Element	Bit 0-31	Polarity N.O./N.C.	Width	Offset
√	√	√			

The "Do Nothing" assignment will run do nothing if it is active or inactive.

Start Supported Feature

Bus	Element	Bit 0-31	Polarity N.O./N.C.	Width	Offset
√	√	√	√		

The "Start" assignment will run the tool while the input is active. Start is available for the Physical I/O bus only.

Stop Supported Feature

Bus	Element	Bit 0-31	Polarity N.O./N.C.	Width	Offset
√	√	√	√		

The "Stop" assignment will stop the tool if it is running and prevent it from being started.

Reverse Supported Feature

Bus	Element	Bit 0-31	Polarity N.O./N.C.	Width	Offset
√	√	√	√		

The "Reverse" will put the controller in disassembly mode while the input is active.

Disable Supported Feature

Bus	Element	Bit 0-31	Polarity N.O./N.C.	Width	Offset
√	√	√	√		

The "Disable" will disable the tool while the input is active. It will not stop a fastening cycle that is progress.

Reset Job Supported Feature

Bus	Element	Bit 0-31	Polarity N.O./N.C.	Width	Offset
√	√	√	√		

On the transition of inactive to active the "Reset Job" assignment will reset the active job.

Select PSet Supported Feature

Bus	Element	Bit 0-31	Polarity N.O./N.C.	Width	Offset
√	√	√		√	√

The "Select PSET" input will select the parameter set according to the input value. Uses the width parameter limit the width of the input bits read. The minimum width is 1 and the maximum is 8. After the input is read the offset parameter will be added to the value do get the actual parameter set number. Selecting an invalid parameter set number will disable the tool.

Select Job Supported Feature

Bus	Element	Bit 0-31	Polarity N.O./N.C.	Width	Offset
√	√	√		√	√

The "Select Job" input will select the job number according to the input value. Uses the width parameter limit the width of the input bits read. The minimum width is 1 and the maximum is 8. After the input is read the offset parameter will be added to the value do get the actual job number. Selecting an invalid job number will disable the tool.

Select Job Sequence Supported Feature

Bus	Element	Bit 0-31	Polarity N.O./N.C.	Width	Offset
√	√	√		√	√

The "Select Job Sequence" input will select the job sequence number according to the input value. Uses the width parameter limit the width of the input bits read. The minimum width is 1 and the maximum is 8. After the input is read the offset parameter will be added to the value do get the actual job sequence number. Selecting an invalid job sequence number or a sequence that is already complete will disable the tool.

Disable Assembly Supported Feature

Bus	Element	Bit 0-31	Polarity N.O./N.C.	Width	Offset
√	√	√	√		

The "Disable Assembly" assignment will disable the tool in the assembly direction. It will not disable the tool in disassembly or tube nut homing. It will not stop a fastening cycle that is progress.

Set ID Supported Feature

Bus	Element	Bit 0-31	Polarity N.O./N.C.	Width	Offset
√	√	√		√	

The "Set ID" assignment will set the ID to an integer value of the input value. The width can be set from 1 to 32 bits. The input value will read as an integer value and an ASCII string with leading zeros will be produced and passed to the ID recognition system. The length of the string is based on the width of the assignment. The string will always be sized to accommodate the maximum value of the input. For example a width setting of 16 can have an integer value of 0-65535 so the produced ID would be "00000" to "65535" (always five character long).

Width setting	Length of ID string	ID value
1 - 3	1	"0" – "n"
4 - 6	2	"00" – "nn"
7 - 9	3	"000" – "nnn"
10 - 13	4	"0000" – "nnnn"
14 - 16	5	"00000" – "nnnnn"
17 – 19	6	"000000" – "nnnnnn"
20 – 23	7	"0000000" – "nnnnnnn"
24 – 26	8	"00000000" – "nnnnnnnn"
27 – 29	9	"000000000" – "nnnnnnnnn"
30 - 32	10	"0000000000" – "nnnnnnnnnn"

Set ID (word swap) Supported Feature

Bus	Element	Bit 0-31	Polarity N.O./N.C.	Width	Offset
√	√	√		√	

The "Set ID (word swap)" assignment is the same as the "Set ID" assignment except the high and low words (16bit) are swapped prior to evaluation. This is to correct the mixed endianness of some PLC. See the "Set ID" for behavior.

Set Date/Time Supported Feature

Bus	Element	Bit 0-31	Polarity N.O./N.C.	Width	Offset
√	√	√		√	

The "Set Date/Time" assignment will set the date and time of the controller. The width can be set from 1 to 32 bits but should always be set to 32 to get the correct results. The input value will be read as the number of seconds since 00:00:00 January 1, 1970 (POSIX time or Epoch time). If the input value changes and it is non-zero the date and time of the controller will be set to the new value.

Set Date/Time (word swap) Supported Feature

Bus	Element	Bit 0-31	Polarity N.O./N.C.	Width	Offset
√	√	√		√	

The "Set Date/Time (word swap)" assignment is the same as the "Set Date/Time" assignment except the high and low words (16bit) are swapped prior to evaluation. This is to correct the mixed endianness of some PLC. See the "Set Date/Time" for behavior.

Verify PSet Supported Feature

Bus	Element	Bit 0-31	Polarity N.O./N.C.	Width	Offset
√	√	√		√	√

The "Verify PSET" input will compare the current parameter set to the input value. Uses the width parameter limit the width of the input bits read. The minimum width is 1 and the maximum is 8. After the input is read the offset parameter will be added to the value do get the actual parameter set number. If the parameter set input value does not match the current parameter of the controller the tool will be disabled.

Clear Results Supported Feature

Bus	Element	Bit 0-31	Polarity N.O./N.C.	Width	Offset
√	√	√	√		

The "Clear Results" assignment will clear the latest results outputs (Ok, Nok, etc.) on the same bus.

Log Change Supported Feature

Bus	Element	Bit 0-31	Polarity N.O./N.C.	Width	Offset
√	√	√		√	

The "Log Change" assignment will add entries to the controller event log when the input changes.

Decrement Batch Supported Feature

Bus	Element	Bit 0-31	Polarity N.O./N.C.	Width	Offset
√	√	√	√		

The "Decrement Batch" assignment will remove the latest OK rundown from the current running JOB. This will cause the JOB count to be reduced by one.

Increment Batch Supported Feature

Bus	Element	Bit 0-31	Polarity N.O./N.C.	Width	Offset
√	√	√	√		

The "Increment Batch" assignment will insert a manual rundown into the current sequence of the current JOB. This will cause the JOB count to increment by one.

Click Wrench Supported Feature

Bus	Element	Bit 0-31	Polarity N.O./N.C.	Width	Offset
√	√	√	√		

The "Click Wrench" assignment is the same as "Increment Batch" with the addition of a programmable torque value.

Bypass Stops Supported Feature

Bus	Element	Bit 0-31	Polarity N.O./N.C.	Width	Offset
√	√	√	√		

The "Bypass Stops" assignment removes most stop conditions, allowing the tool to be ran in an override type condition. Hardware faults, stop and disable inputs are not removed.

Verify Job Sequence Supported Feature

Bus	Element	Bit 0-31	Polarity N.O./N.C.	Width	Offset
√	√	√		√	√

The "Verify Job Sequence" input will compare the current Job sequence to the input value. Uses the width parameter limit the width of the input bits read. The minimum width is 1 and the maximum is 8. After the input is read the offset parameter will be added to the value do get the actual Job sequence number. If the Job sequence input value does not match the current Job sequence of the controller the tool will be disabled.

ASCII ID Supported Feature

Bus	Element	Bit 0-31	Polarity N.O./N.C.	Width	Offset
√	√				

Abort Job Supported Feature

Bus	Element	Bit 0-31	Polarity N.O./N.C.	Width	Offset
√	√	√	√		

The "Abort Job" assignment , aborts the job and disables the tool. A job reset is required to enable the tool for the next job.

Remote Start Supported Feature

Bus	Element	Bit 0-31	Polarity N.O./N.C.	Width	Offset
√	√	√	√		

The "Remote Start" assignment will run the tool while the input is active. Remote Start is available for non-physical I/O buses.

Remove Lock on Reject Supported Feature

Bus	Element	Bit 0-31	Polarity N.O./N.C.	Width	Offset
√	√	√	√		

The "Remove Lock on Reject" assignment unlocks the tool if locked on reject, re-enabling the tool.

Outputs

All output assignments have a Bus, Element, and Bit configuration to define its location in the system. Along with the basic configuration many also have other configuration(s) that allow its behavior to be modified to suit the application.

	Supported Feature											Controller				
	Bus	Element	Bit 0-32	Polarity N.O./ N.C.	Mode Normal, Timed, Flashed	Time	Width	Offset	Input Bus	Input Element	Input Bit	iEC	iAC	iPC	iBC	iBC-Z
Ok	√	√	√	√	√							√	√	√	√	√
Nok	√	√	√	√	√							√	√	√	√	√
Torque Ok	√	√	√	√	√							√	√	√	√	√
Torque Nok	√	√	√	√	√							√	√	√	√	√
Low Torque	√	√	√	√	√							√	√	√	√	√
High Torque	√	√	√	√	√							√	√	√	√	√
Angle Ok	√	√	√	√	√							√	√	√	√	√
Angle Nok	√	√	√	√	√							√	√	√	√	√
Low Angle	√	√	√	√	√							√	√	√	√	√
High Angle	√	√	√	√	√							√	√	√	√	√
Fastening Complete	√	√	√	√	√							√	√	√	√	√
In Cycle	√	√	√	√	√							√	√	√		
Fastening Aborted	√	√	√	√	√							√	√	√	√	√
Fastening Stopped	√	√	√	√	√							√	√	√	√	√
Batch Complete	√	√	√	√	√							√	√	√	√	√
Job Complete	√	√	√	√	√							√	√	√	√	√
Error	√	√	√	√	√							√	√	√	√	√
Tool Start Switch	√	√	√	√	√							√				
Tool Push to Start Switch	√	√	√	√	√							√				
Tool MFB	√	√	√	√	√							√				
Tool Enabled	√	√	√	√	√							√	√	√	√	√
Tool Running	√	√	√	√	√							√				
Service Indicator	√	√	√	√	√							√	√	√		√
ToolsNet Connected	√	√	√	√	√							√	√	√	√	√
Open Protocol Connected	√	√	√	√	√							√	√	√	√	√
PFCS Connected	√	√	√	√	√							√	√	√	√	√
Running PSet Number	√	√	√				√	√				√	√	√	√	√
Running Job Number	√	√	√				√	√				√	√	√	√	√
External Controlled	√	√	√						√	√	√	√	√	√	√	√
Tool In CCW	√	√	√	√	√							√				
Tool In CW	√	√	√	√	√							√				
Torque	√	√	√				√					√	√	√	√	√
Torque (x10)	√	√	√				√					√	√	√	√	√
Torque (x100)	√	√	√				√					√	√	√	√	√
Angle	√	√	√				√					√	√	√	√	√
Rundown Saved to FTP Server	√	√	√				√					√	√	√	√	√
Fastener Removed	√	√	√	√	√							√	√	√		
Spindle Ok	√	√	√	√	√							√				
Spindle NOk	√	√	√	√	√							√				
Spindle Fastening Complete	√	√	√	√	√							√				
Pulses	√	√	√				√						√	√		√
Pulses High	√	√	√	√	√								√	√		√
Pulses Low	√	√	√	√	√								√	√		√
Pulses NOk	√	√	√	√	√								√	√		√
Pulses Ok	√	√	√	√	√								√	√		√
ON	√	√	√	√	√							√	√	√	√	√
Job Aborted	√	√	√	√	√							√	√	√	√	
Tool In Use	√	√	√	√		√						√	√	√	√	√
Barcode Scanned	√	√	√	√								√	√	√	√	√

Polarity
When the polarity is set to N.O. the output will be high when it is active (24vdc for physical outputs and logic 1 for all network type buses). When the polarity is set to N.C. the output will be low for active (0vdc for physical inputs and logic 0 for all network type buses).

Mode

Normal
In the "Normal" mode the output will track the state of the assignment (while still observing the polarity setting). If the polarity is set N.O. and the assignment has an active output the output will be on and stay on till the assignment goes to inactive.

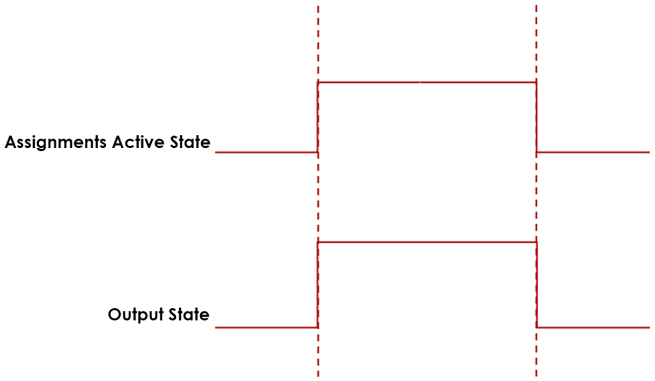


Figure 1: Normal Mode

Timed
In the "Timed" mode the output will come on when the assignments state goes active and go off based on the time value or the assignment state going inactive (while still observing the polarity setting).

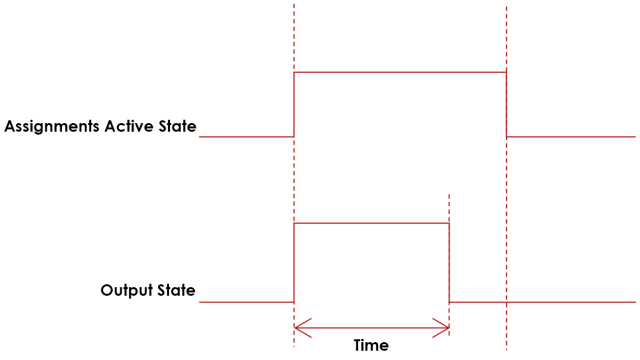


Figure 2 Timed Mode

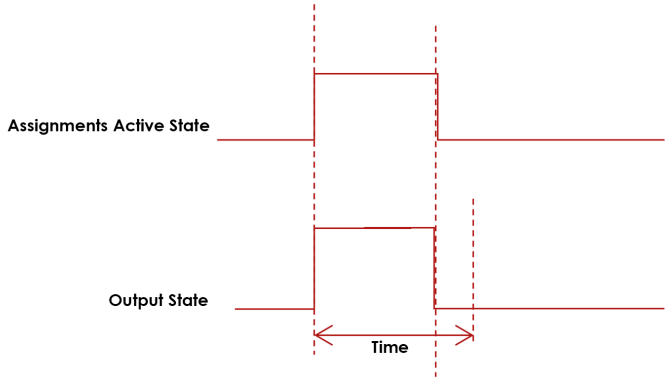


Figure 3: Timed Mode (assignment deactivates before time expires)

Flash
In the "flash" mode the output will flash at the time rate while the assignments state is active (while still observing the polarity setting).

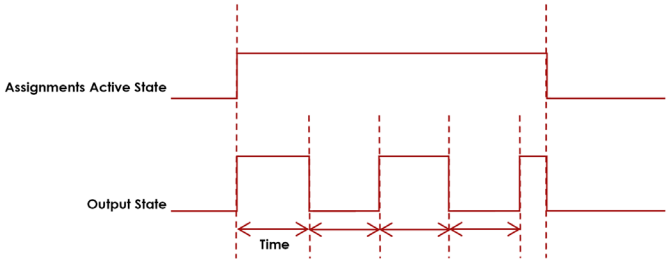


Figure 3 Flash Mode

Width and Offset
For multiple bit outputs (for example "Running PSet Number") the width variable defines the number of bits the assignment will output. This allows the output size to be restricted to a few bits saving space for other assignments.

The offset variable allows a fixed value to be added to the value before it is output.

For example to use bits 4 & 5 of the physical outputs to indicate the selected parameter set number 1-4 as binary 0-3 the assignment would look like…

Running PSet Number		
Bus	1	For the physical bus
Element	0	For the first element on the bus
Bit	4	For the starting bit location
Width	2	To span the two bits 4 & 5
Offset	-1	Adding -1 to the read input value so we get… 1 = Binary 00 2 = Binary 01 3 = Binary 10 4 = Binary 11

Output Assignments

Ok *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Ok" output assignment will go active at the completion of an acceptable fastening. It will go inactive when the next fastening is started (the torque exceeds the threshold value) or a Job reset.

Nok *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Nok" output assignment will go active at the completion of an unacceptable fastening. It will go inactive when the next fastening is started (the torque exceeds the threshold value) or a Job reset.

Torque Ok *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Torque Ok" output assignment will go active at the completion of a fastening that has an acceptable torque value. It will go inactive when the next fastening is started (the torque exceeds the threshold value) or a Job reset.

Torque Nok *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Torque Nok" output assignment will go active at the completion of a fastening that has an unacceptable torque value. It will go inactive when the next fastening is started (the torque exceeds the threshold value) or a Job reset.

Low Torque *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Low Torque" output assignment will go active at the completion of a fastening that has a low torque results. It will go inactive when the next fastening is started (the torque exceeds the threshold value) or a Job reset.

High Torque *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "High Torque" output assignment will go active at the completion of a fastening that has a high torque results. It will go inactive when the next fastening is started (the torque exceeds the threshold value) or a Job reset.

Angle Ok *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Angle Ok" output assignment will go active at the completion of a fastening that has an acceptable angle results. It will go inactive when the next fastening is started (the torque exceeds the threshold value) or a Job reset.

Angle Nok *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Angle Nok" output assignment will go active at the completion of a fastening that has an unacceptable angle results. It will go inactive when the next fastening is started (the torque exceeds the threshold value) or a Job reset.

Low Angle *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Low Angle" output assignment will go active at the completion of a fastening that has a low angle results. It will go inactive when the next fastening is started (the torque exceeds the threshold value) or a Job reset.

High Angle *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "High Angle" output assignment will go active at the completion of a fastening that has high angle results. It will go inactive when the next fastening is started (the torque exceeds the threshold value) or a Job reset.

Fastening Complete *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Fastening Complete" output assignment will go active at the completion of a fastening. It will go inactive when the next fastening is started (the torque exceeds the threshold value) or a Job reset.

In Cycle *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "In Cycle" output assignment will go active at the start of the fastening cycle (the torque exceeds the threshold value). It will go inactive when the fastening cycle ends.

Fastening Aborted *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Fastening Aborted" output assignment will go active at the completion of a fastening that was aborted by the system. It will go inactive when the next fastening is started (the torque exceeds the threshold value) or a Job reset.

Fastening Stopped *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Fastening Stopped" output assignment will go active at the completion of a fastening that was stopped by the user. It will go inactive when the next fastening is started (the torque exceeds the threshold value) or a Job reset.

Batch Complete *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Batch Complete" output assignment will go active at the completion of a fastening that satisfies the bolt count of a Job sequence. It will go inactive when the next fastening is started (the torque exceeds the threshold value) or the job is reset.

Job Complete *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Job Complete" output assignment will go active at the completion of a fastening that satisfies all the sequences. It will go inactive when the next fastening is started (the torque exceeds the threshold value) or the job is reset.

Error *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Error" output assignment will be active while the controller has an error.

Tool Start Switch *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Tool Start Switch" output assignment will reflect the state of the tools start lever.

Tool Push to Start Switch *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Tool Push to Start Switch" output assignment will reflect the state of the tools push to start switch.

Tool MFB *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Tool MFB" output assignment will reflect the state of the tools multifunction button.

Tool Enabled *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Tool Enabled" output assignment will be active if the tool is enabled.

Tool Running *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Tool Running" output assignment will be active while the tool is running.

Service Indicator *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Service Indicator" output assignment will be active if the system is in need of service.

ToolsNet Connected *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "ToolsNet Connected" output assignment will be active if the controller has an active connection to a ToolsNet server.

Open Protocol Connected *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Open Protocol Connected" output assignment will be active if the controller has an active Open protocol connection.

PFCS Connected *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "PFCS Connected" output assignment will be active if the controller has an active PFCS connection.

Running PSet Number *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√				√	√			

The "Running PSet Number" output assignment will output the current PSet number.

Running Job Number *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√				√	√			

The "Running Job Number" output assignment will output the current Job number.

External Controlled *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√						√	√	√

The "External Controlled" output assignment will reflect the state of an input. Use the "Input Bus, "Input Element", and "Input Bit" to specify the input to reflect.

Tool In CCW *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Tool In CCW" output assignment will be active if the tool is put into disassembly mode and inactive if the tool is in assembly mode.

Tool In CW *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Tool In CW" output assignment will be active when the is in assembly mode and inactive if the tool is put into disassembly mode.

Torque *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√				√				

The "Torque" output assignment will output the final torque value of the most recent rundown. The value will be cleared to 0 at the start of a new fastening cycle or a Job reset. At the end of the fastening cycle the final torque will be truncated to an integer and output.

Torque (x10) *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√				√				

The "Torque (x10)" output assignment will output the final torque value of the most recent rundown. The value will be cleared to 0 at the start of a new fastening cycle or a Job reset. At the end of the fastening cycle the final torque will be multiplied by 10, truncated to an integer and output.

Torque (x100) *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√				√				

The "Torque (x100)" output assignment will output the final torque value of the most recent rundown. The value will be cleared to 0 at the start of a new fastening cycle or a Job reset. At the end of the fastening cycle the final torque will be multiplied by 100, truncated to an integer and output.

Angle *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√				√				

The "Angle" output assignment will output the final angle value of the most recent rundown. The value will be cleared to 0 at the start of a new fastening cycle or a Job reset.

Rundown Saved to FTP Server *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√				√				

The "Rundown Saved to FTP Server" output assignment will output the ID of the last rundown that was saved to the FTP server.

Fastener Removed *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Fastener Removed" output assignment will go active when a fastener is removed by the operator. The controller must be configured to report disassembly for this output to work. It will go inactive when the next fastening is started (the torque exceeds the threshold value) or a Job reset.

Spindle Ok *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Spindle Ok" output assignment will go active at the completion of multi-spindle fastening if all spindles have an OK. It will go inactive when the next fastening is started (the torque exceeds the threshold value) or a Job reset.

Spindle NOk *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Spindle NOk" output assignment will go active at the completion of multi-spindle fastening if one or more of the spindles have an NOK. It will go inactive when the next fastening is started (the torque exceeds the threshold value) or a Job reset.

Spindle Fastening Complete *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Spindle Fastening Complete" output assignment will go active at the completion of multi-spindle fastening. It will go inactive when the next fastening is started (the torque exceeds the threshold value) or a Job reset.

Pulses *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√				√				

The "Pulses" output assignment will output the pulse count value of the most recent rundown. The value will be cleared to 0 at the start of a new fastening cycle or a Job reset.

Pulses Ok *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Pulses Ok" output assignment will go active at the completion of a fastening that has an acceptable pulse count. It will go inactive when the next fastening is started (the torque exceeds the threshold value) or a Job reset.

Pulses NOk *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Pulses NOk" output assignment will go active at the completion of a fastening that has an unacceptable pulse count. It will go inactive when the next fastening is started (the torque exceeds the threshold value) or a Job reset.

Pulses High *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Pulses High" output assignment will go active at the completion of a fastening that has an pulse count that exceeds the high limit. It will go inactive when the next fastening is started (the torque exceeds the threshold value) or a Job reset.

Pulses Low *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Pulses Low" output assignment will go active at the completion of a fastening that has an pulse count that falls below the low limit. It will go inactive when the next fastening is started (the torque exceeds the threshold value) or a Job reset.

ON *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "ON" output assignment will be active when the controller is powered up and remains active until power down.

Job Aborted *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√	√						

The "Job Aborted" output assignment will go active if a Job is aborted. It will go inactive when the job is reset.

Tool In Use *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√		√					

The "Tool In Use" output assignment will go active when the trigger is pressed, whereupon a timer will restart. It will go inactive when the specified time is reached without becoming active in between.

Barcode Scanned *Supported Feature*

Bus	Element	Bit 0-32	Polarity N.O./N.C.	Mode Normal, Timed, Flash	Time	Width	Offset	Input Bus	Input Element	Input Bit
√	√	√	√							

The "Barcode Scanned" output assignment will go active when a barcode is scanned. The ID # (1-4) will activate the corresponding bit, if it is covered by the number of bits configured. The maximum size is 4 bits. All bits will go inactive when a tool reaches the InCycle threshold of a rundown or when they are reset.

10. Controller Supported MIDs

Supported MID			
MID	Description	Revisions	Note
1	Communication start	1,2,3	
2	Communication start acknowledge	1,2,3	
3	Communication stop		
4	Command error		
5	Command accepted		
10	Parameter set ID upload request		
11	Parameter set ID upload reply		
14	Parameter set selected subscribe		
15	Parameter set selected		
16	Parameter set selected acknowledge		
17	Parameter set selected unsubscribe		
18	Select Parameter set		
19	Set Parameter set batch size		
20	Reset Parameter set batch counter		
30	Job ID upload request		
31	Job ID upload reply		
34	Job info subscribe		
35	Job info		
36	Job info acknowledge		
37	Job info unsubscribe		
38	Select Job		
39	Job restart		
40	Tool data upload request	1,2	
41	Tool data upload reply		
42	Disable tool		
43	Enable tool		
50	Vehicle ID number download request		
51	Vehicle ID number subscribe	1,2	
52	Vehicle ID number		
53	Vehicle ID number acknowledge		
54	Vehicle ID number unsubscribe		
60	Last tightening result data subscribe	1,2,3,999	
61	Last tightening result data		
62	Last tightening result data acknowledge		
63	Last tightening result data unsubscribe		
64	Old tightening result upload request		
65	Old tightening result upload reply		

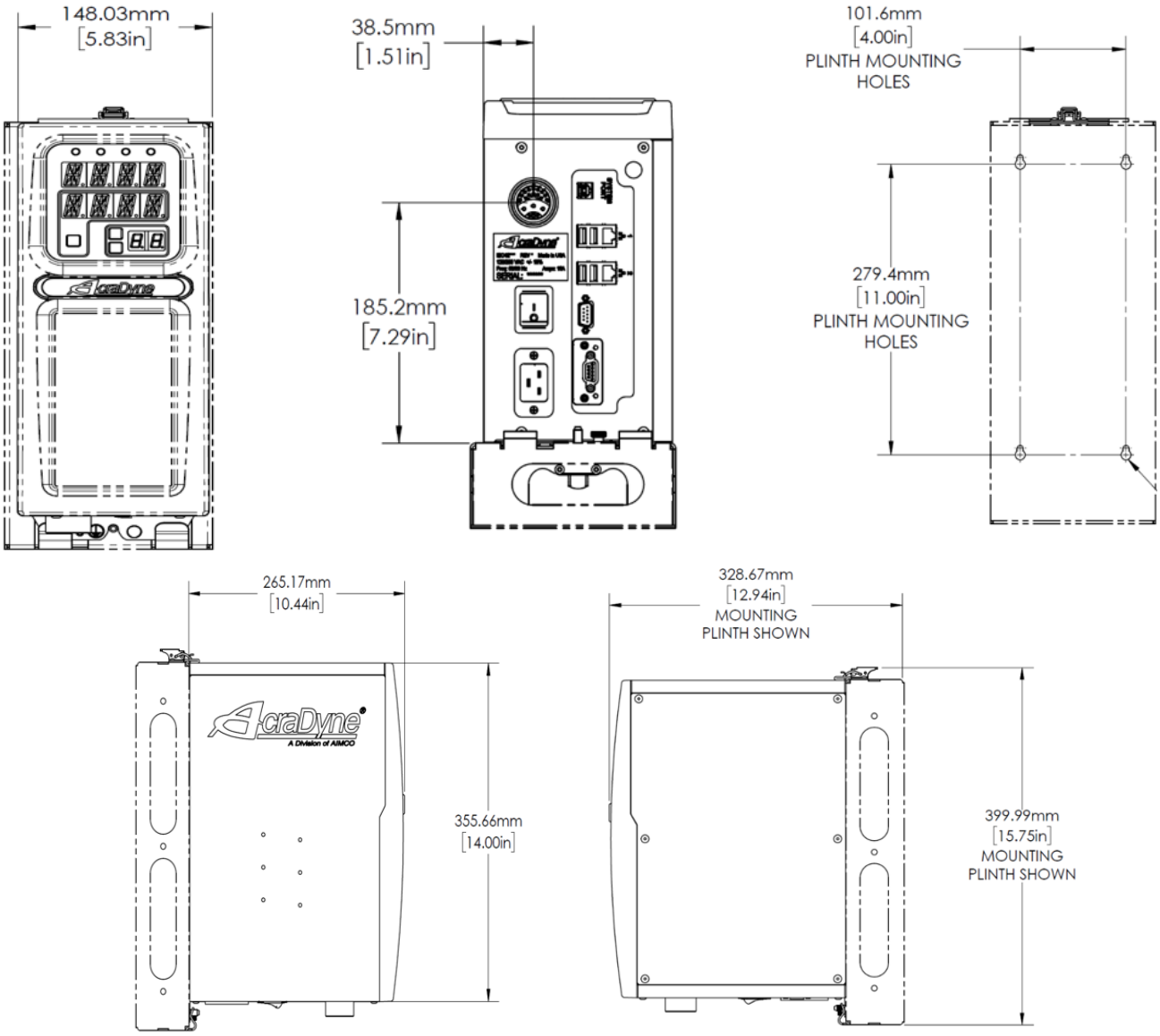
Supported MID			
MID	Description	Revisions	Note
70	Alarm subscribe		
71	Alarm		
72	Alarm acknowledge		
73	Alarm unsubscribe		
76	Alarm status		
77	Alarm status acknowledge		
80	Read time upload request		
81	Read time upload reply		
82	Set time		
90	Multi spindle status subscribe		
91	Multi spindle status		
92	Multi spindle status acknowledge		
91	Multi spindle status unsubscribe		
100	Multi spindle results subscribe		
101	Multi spindle results subscribe		
102	Multi spindle results acknowledge		
103	Multi spindle results unsubscribe		
113	Flash green light on tool		
127	Abort Job		
128	Job batch increment		
129	Job batch decrement		
130	Job off		
150	Identifier download request		
157	Reset all Identifiers		
200	Set external controlled relays		Only supports 0 (off) and 1 (on)
210	Status external monitored inputs subscribe		
211	Status external monitored inputs		
212	Status external monitored inputs acknowledge		
213	Status external monitored inputs unsubscribe		
214	IO device status request	1,2	
215	IO device status reply		
216	Relay function subscribe		See supported relay functions below.
217	Relay function		
218	Relay function acknowledge		
219	Relay function unsubscribe		
9999	Keep alive open protocol communication		

Supported Relay Functions

Supported Relay Functions	
Number	Function
1	OK
2	NOK
5	Low Torque
6	High Torque
7	Low angle
8	High angle
9	Cycle complete
10	Alarm

Supported Relay Functions	
Number	Function
11	Batch NOK
12	Job OK
19	Tool ready
20	Tool start switch
21	Dir. switch = CW
22	Dir. switch = CCW
26	Tool running
276	Cycle abort

11. Dimensions



12. Specifications

Mechanical:

Dimensions	Width:	6.25 in	159 mm
	Height:	15.75 in	400 mm
	Depth:	12.5 in	316 mm
Weight:		15.65 lbs	7.1 kg

Operating Conditions:

Temperature:	32 to 122 °F (0 to 50 °C)
Humidity:	Non-condensing
Ingress Protection:	IP20

Electrical:

AC Power Source:	
120 VAC, 1Φ, 50/60 Hz.	
240 VAC, 1Φ, 50/60 Hz.	84 W,3.5 Amps

Standards:

Safety Compliance:
EC Machinery Directive 2006/42/EC EC Low Voltage Directive 2006/95/EC EN 12100-1; EN 12100-12 Safety of Machinery EN 60745-1; EN 60745-2-2 Hand-held motor operated tools
EMC
EC Directive of Electromagnetic Compatibility 2004/108/EC EN 61000-6-4; EN 6100-6-2; Class A
RoHs
Reduction of Hazardous Substances 2002/95/EC
Markings
CE

13. Troubleshooting

Issue: SD Card initializing

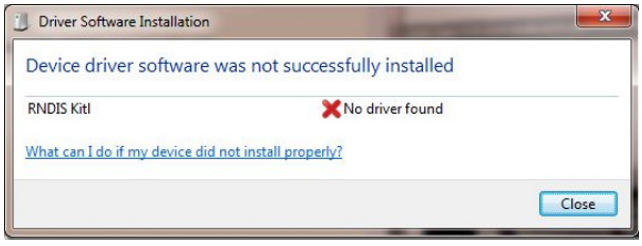
Solution: The rear SD card can be used to easily move the software, firmware, configuration, and rundowns to a new controller in the event of hardware failure. This allows the controller to be replaced with a new unit while retaining all the rundown information and configuration settings. Remove the rear SD card from the damaged unit and insert it into a functioning unit to perform the replacement. It is highly recommended that the controller settings are backed up and saved by exporting the controller to a USB flash drive.

Issue: System Port IP Address Drivers

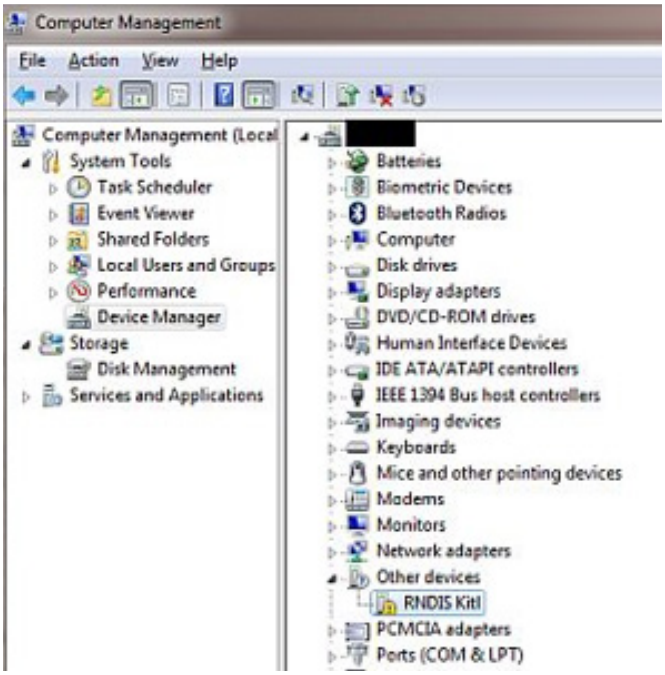
Solution: NOTE: In the event the RNDIS drivers do not install themselves, the following are the steps to install new drivers in order to get the system port working.

RNDIS driver is a part of the Windows 7 operating system, but the OS fails to detect it automatically. The following steps will help the user to install the RNDIS driver:

Step 1: After the device is connected to the development PC, OS will automatically search for the RNDIS driver. After it fails to find the driver, the following message will be shown:



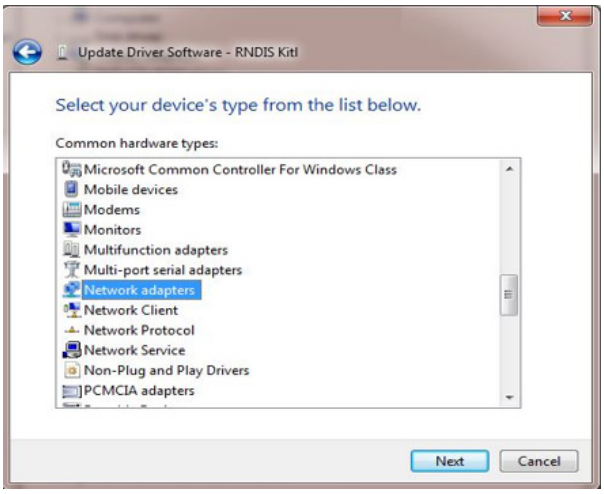
Step 2: Right click on **Computer** and select **Manage.** From **System Tools,** select **Device Manager.** It will show a list of devices currently connected with the development PC. In the list, RNDIS Kitl can be seen with an exclamation mark implying that driver has not been installed.



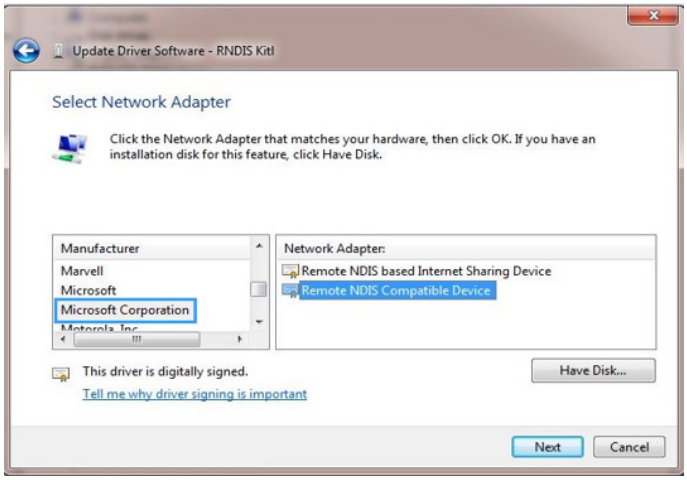
Step 3: Right click on it and select **Update Driver Software**. When prompted, choose **Browse my computer for driver software** to search for device driver software.

Step 4: **Browse for driver software on your computer** will come up. Select **Let me pick from a list of device drivers on my computer**.

Step 5: A window will come up asking to select the device type. Select **Network Adapters** as RNDIS emulates a network connection.

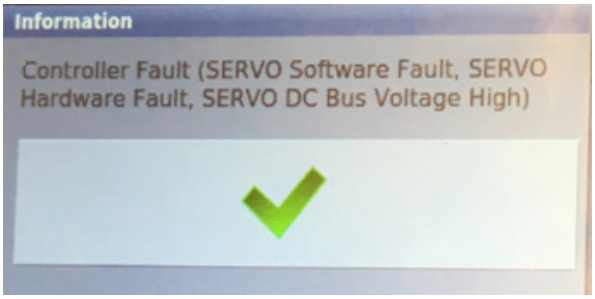


Step 6: In the **Select Network Adapter** window, select **Microsoft Corporation** from the **Manufacturer** list. Under the list of **Network Adapter**, select **Remote NDIS Compatible Device**.



Step 7: The RNDIS Kitl device is now installed and ready for use.

Issue: DC Bus High Voltage Warning when using an HT Tool



Solution: Adding a Brake Stop of 0.5 to 1.0 Second stage to the end of the rundown should eliminate this issue.

14. AIMCO Warranty

NEW TOOL AND ACCESSORY WARRANTY
Any new tool or accessory branded with the AIMCO, Uryu, AcraDyne or Eagle Group name, and purchased from AIMCO, or through one of its authorized distributors or agents, is warranted to the original buyer against defects in materials and workmanship for a period of one (1) year* from date of delivery. Under the terms of this warranty, AIMCO agrees, without charge, to repair or replace, at its option and Ex-Works (EXW) its authorized service centers, any product or accessory warranted hereunder proving to AIMCO's satisfaction to be defective as a result of defective workmanship or material. In order to qualify for this warranty, written notice to AIMCO must be given immediately upon discovery of such defect, at which time AIMCO will issue an authorization to return the tool. The defective item must be promptly returned to an authorized AIMCO service center with all freight charges prepaid.

REPAIRED TOOL WARRANTY
Once a tool is beyond the new product warranty period as detailed above, AIMCO will provide repair subject to the following warranty periods: pneumatic tools: 90 days*; electric tools and Acra-Feed: 90 days; battery tools: 30 days*; DC Electric tools: 90 days*

EXCLUSION FROM WARRANTY
This warranty is valid only on products purchased from AIMCO, or through its authorized distributors or agents. AIMCO shall have no obligation pursuant to the AIMCO Warranty with respect to any tools or accessories which in AIMCO's sole judgment have been altered damaged, misused, abused, badly worn, lost or improperly maintained. This Warranty is null and void if the customer, or any other person other than an authorized representative of AIMCO, has made any attempt to service or modify the tool or accessory prior to its return to AIMCO under this Warranty.

The warranty provision with respect to each such product may be amended by AIMCO from time to time in its sole discretion. The liability of AIMCO hereunder shall be limited to replacing or repairing, at its option, any defective products which are returned freight pre-paid to AIMCO or, at AIMCO's option, refunding the purchase price of such products.

AIMCO reserves the right to make periodic changes in construction or tool design at any time. AIMCO specifically reserves the right to make these changes without incurring any obligation or incorporating such changes or updates in tools or parts previously distributed.

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NOTE: The AIMCO Warranty confers specific legal rights, however some states or jurisdictions may not allow certain exclusions or limitations within this warranty. ***Note – All warranty periods addressed herein are determined using a standard shift, eight-hour work day.**

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